

TS 18508 Additional Parallel Features in Fortran

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Foreword

ISO (the International Organization for Standardization) and IEC (the International Electrotechnical Commission) form the specialized system for worldwide standardization. National bodies that are members of ISO or IEC participate in the development of International Standards through technical committees established by the respective organization to deal with particular fields of technical activity. ISO and IEC technical committees collaborate in fields of mutual interest. Other international organizations, governmental and nongovernmental, in liaison with ISO and IEC, also take part in the work. In the field of information technology, ISO and IEC have established a joint technical committee, ISO/IEC JTC 1.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of the joint technical committee is to prepare International Standards. Draft International Standards adopted by the joint technical committee are circulated to national bodies for voting. Publication as an International Standard requires approval by at least 75 % of the national bodies casting a vote.

In other circumstances, particularly when there is an urgent market requirement for such documents, the joint technical committee may decide to publish an ISO/IEC Technical Specification (ISO/IEC TS), which represents an agreement between the members of the joint technical committee and is accepted for publication if it is approved by 2/3 of the members of the committee casting a vote.

An ISO/IEC TS is reviewed after three years in order to decide whether it will be confirmed for a further three years, revised to become an International Standard, or withdrawn. If the ISO/IEC TS is confirmed, it is reviewed again after a further three years, at which time it must either be transformed into an International Standard or be withdrawn.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO and IEC shall not be held responsible for identifying any or all such patent rights.

ISO/IEC TS 18508:2015 was prepared by Joint Technical Committee ISO/IEC JTC 1, *Information technology*, Subcommittee SC22, *Programming languages, their environments and system software interfaces*.

Introduction

The system for parallel programming in Fortran, as standardized by ISO/IEC 1539-1:2010, defines simple syntax for access to data on another image of a program, synchronization statements for controlling the ordering of execution segments between images, and collective allocation and deallocation of memory on all images.

The existing system for parallel programming does not provide for an environment where a subset of the images can easily work on part of an application while not affecting other images in the program. This complicates development of independent parts of an application by separate teams of programmers. The existing system does not provide a mechanism for a processor to identify what images have failed during execution of a program. This adversely affects the resilience of programs executing on large systems. The synchronization primitives available in the existing system do not provide a convenient mechanism for ordering execution segments on different images without requiring that those images arrive at a synchronization point before either is allowed to proceed. This introduces unnecessary inefficiency into programs. Finally, the existing system does not provide intrinsic procedures for commonly used collective and atomic memory operations. Intrinsic procedures for these operations can be highly optimized for the target computational system, providing significantly improved program performance.

This Technical Specification extends the facilities of Fortran for parallel programming to provide for grouping the images of a program into nonoverlapping teams that can more effectively execute independently parts of a larger problem, for the processor to indicate which images have failed during execution and allow continued execution of the program on the remaining images, for a system of events that can be used for fine grain ordering of execution segments, and for collective and atomic memory operation subroutines that can provide better performance for specific operations involving more than one image.

The facility specified in this Technical Specification is a compatible extension of Fortran as standardized by ISO/IEC 1539-1:2010, ISO/IEC 1539-1:2010/Cor 1:2012, and ISO/IEC 1539-1:2010/Cor 2:2013.

It is the intention of ISO/IEC JTC 1/SC22 that the semantics and syntax specified by this Technical Specification be included in the next revision of ISO/IEC 1539-1 without change unless experience in the implementation and use of this feature identifies errors that need to be corrected, or changes are needed to achieve proper integration, in which case every reasonable effort will be made to minimize the impact of such changes on existing implementations.

This Technical Specification is organized in 8 clauses:

Scope	Clause 1
Normative references	Clause 2
Terms and definitions	Clause 3
Compatibility	Clause 4
Teams of images	Clause 5
Failed images	Clause 6
Events	Clause 7
Intrinsic procedures	Clause 8
Required editorial changes to ISO/IEC 1539-1:2010(E)	Clause 9

It also contains the following nonnormative material:

Extended notes	Annex A
----------------	-------------------------

1 Scope

2 This Technical Specification specifies the form and establishes the interpretation of facilities that extend the For-
3 tran language defined by ISO/IEC 1539-1:2010, ISO/IEC 1539-1:2010/Cor 1:2012, and ISO/IEC 1539-1:2010/Cor
4 2:2013. The purpose of this Technical Specification is to promote portability, reliability, maintainability, and ef-
5 ficient execution of parallel programs written in Fortran, for use on a variety of computing systems.

6 This Technical Specification does not specify formal data consistency or progress models. Some level of asyn-
7 chronous progress is required to ensure the correct execution of the examples in Annex A that illustrate the
8 semantics described in clauses 7 and 8. Developing the formal data consistency and progress models is left until
9 the integration of these facilities into ISO/IEC 1539-1.

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1 2 Normative references

2 The following referenced standards are indispensable for the application of this document. For dated references,
3 only the edition cited applies. For undated references, the latest edition of the referenced document (including
4 any amendments) applies.

5 ISO/IEC 1539-1:2010, *Information technology—Programming languages—Fortran—Part 1:Base language*

6 ISO/IEC 1539-1:2010/Cor 1:2012, *Information technology—Programming languages—Fortran—Part 1:Base lan-*
7 *guage TECHNICAL CORRIGENDUM 1*

8 ISO/IEC 1539-1:2010/Cor 2:2013, *Information technology—Programming languages—Fortran—Part 1:Base lan-*
9 *guage TECHNICAL CORRIGENDUM 2*

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3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO/IEC 1539-1:2010 and the following apply. The intrinsic module ISO_FORTRAN_ENV is extended by this Technical Specification.

3.1

active image

An image that has not failed or initiated termination

3.2

asynchronous progress

ability of images to define or reference coarrays without requiring the images on which the data reside to execute any particular statements

3.3

collective subroutine

intrinsic subroutine that is invoked on the active images of the current team to perform a calculation on those images and assign the computed value on one or all of them (8.3)

3.4

established coarray

coarray that is accessible within a CHANGE TEAM construct from outside the construct (5.1)

3.5

team

set of images that can readily execute independently of other images (5.1)

3.5.1

current team

the team specified in the CHANGE TEAM statement of the innermost executing CHANGE TEAM construct, or the initial team if no CHANGE TEAM construct is active (5.1)

3.5.2

initial team

the current team when the program began execution (5.1)

3.5.3

parent team

team from which the current team was formed by executing a FORM TEAM statement (5.1)

3.5.4

team identifier

integer value identifying a team (5.1)

3.6

failed image

an image for which references or definitions of a variable on the image fail when that variable should be accessible; or an image that is not a stopped image and fails to respond during the execution of an image control statement or a reference to a collective subroutine (6.1)

3.7

stopped image

1 an image that has initiated normal termination

2 **3.8**

3 **event variable**

4 scalar variable of type EVENT_TYPE (7.2) in the intrinsic module ISO_FORTRAN_ENV

5 **3.9**

6 **team variable**

7 scalar variable of type TEAM_TYPE (5.2) in the intrinsic module ISO_FORTRAN_ENV

1 **4 Compatibility**

2 **4.1 New intrinsic procedures**

3 This Technical Specification defines intrinsic procedures in addition to those specified in ISO/IEC 1539-1:2010.
4 Therefore, a Fortran program conforming to ISO/IEC 1539-1:2010 might have a different interpretation under
5 this Technical Specification if it invokes an external procedure having the same name as one of the new intrinsic
6 procedures, unless that procedure is specified to have the EXTERNAL attribute.

7 **4.2 Fortran 2008 compatibility**

8 This Technical Specification specifies an upwardly compatible extension to ISO/IEC 1539-1:2010, as modified by
9 ISO/IEC 1539-1:2010/Cor 1:2012 and ISO/IEC 1539-1:2010/Cor 2:2013.

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5 Teams of images

5.1 Introduction

A team of images is a set of images that can readily execute independently of other images. Syntax and semantics of *image-selector* (R624 in ISO/IEC 1539-1:2010) are extended to determine how cosubscripts are mapped to image indices for both sibling and ancestor team references. Initially, the current team consists of all images and this is known as the initial team. Except for the initial team, every team has a unique parent team. A team is divided into new teams by executing a FORM TEAM statement. Each new team is identified by an integer value known as its team identifier. Information about the team to which the current image belongs can be determined by the processor from the collective value of the team variables on the images of the team.

The current team is the team specified in the CHANGE TEAM statement of the innermost executing CHANGE TEAM construct, or the initial team if no CHANGE TEAM construct is active.

A nonallocatable coarray that is neither a dummy argument, host associated with a dummy argument, declared as a local variable of a subprogram, nor declared in a BLOCK construct is established in the initial team. An allocated allocatable coarray is established in the team in which it was allocated. An unallocated allocatable coarray is not established. An associating coarray is established in the team of its CHANGE TEAM construct. A nonallocatable coarray that is a dummy argument or host associated with a dummy argument is established in the team in which the procedure was invoked. A nonallocatable coarray that is a local variable of a subprogram or host associated with a local variable of a subprogram is established in the team in which the procedure was invoked. A nonallocatable coarray declared in a BLOCK construct is established in the team in which the BLOCK statement was executed. A coarray dummy argument is not established in any ancestor team even if the corresponding actual argument is established in one or more of them.

5.2 TEAM_TYPE

TEAM_TYPE is a derived type with private components. It is an extensible type with no type parameters. Each component is fully default initialized. A scalar variable of this type describes a team. TEAM_TYPE is defined in the intrinsic module ISO_FORTRAN_ENV.

A scalar variable of type TEAM_TYPE is a team variable. The default initial value of a team variable shall not represent any valid team.

5.3 CHANGE TEAM construct

The CHANGE TEAM construct changes the current team to which the executing image belongs.

R501	<i>change-team-construct</i>	is	<i>change-team-stmt</i> <i>block</i> <i>end-change-team-stmt</i>
R502	<i>change-team-stmt</i>	is	[<i>team-construct-name</i> :] CHANGE TEAM (<i>team-variable</i> ■ ■ [<i>coarray-association-list</i>] [<i>sync-stat-list</i>])
R503	<i>coarray-association</i>	is	<i>codimension-decl</i> => <i>coselector-name</i>
R504	<i>end-change-team-stmt</i>	is	END TEAM [(<i>sync-stat-list</i>)] [<i>team-construct-name</i>]

- 1 R505 *team-variable* is *scalar-variable*
- 2 C501 (R501) A branch within a CHANGE TEAM construct shall not have a branch target that is outside the
3 construct.
- 4 C502 (R501) A RETURN statement shall not appear within a CHANGE TEAM construct.
- 5 C503 (R501) An *exit-stmt* or *cycle-stmt* within a CHANGE TEAM construct shall not belong to an outer
6 construct.
- 7 C504 (R501) If the *change-team-stmt* of a *change-team-construct* specifies a *team-construct-name*, the corres-
8 ponding *end-change-team-stmt* shall specify the same *team-construct-name*. If the *change-team-stmt* of a
9 *change-team-construct* does not specify a *team-construct-name*, the corresponding *end-change-team-stmt*
10 shall not specify a *team-construct-name*.
- 11 C505 (R503) The *coarray-name* in the *codimension-decl* shall not be the same as any *coselector-name* in the
12 *change-team-stmt* or the same as a *coarray-name* in another *codimension-decl* in the *change-team-stmt*.
- 13 C506 (R505) A *team-variable* shall be of type TEAM_TYPE (5.2).
- 14 C507 (R502) No *coselector-name* shall appear more than once in a *change-team-stmt*.
- 15 C508 (R503) A *coselector-name* shall be the name of an accessible coarray.

16 A coselector name identifies a coarray. The coarray shall be established when the CHANGE TEAM statement
17 begins execution.

18 The value of *team-variable* shall be the value of a team variable defined by execution of a FORM TEAM statement
19 in the team that executes the CHANGE TEAM statement or be the value of a team variable for the initial team.
20 The values of the *team-variables* on the active images of the team shall be those of team variables defined by
21 execution of the same FORM TEAM statement on all active images of the team or be the values of team variables
22 for the initial team. The current team for the statements of the CHANGE TEAM *block* is the team specified by
23 the value of the *team-variable*. The current team is not changed by a redefinition of the team variable during
24 execution of the CHANGE TEAM construct. A CHANGE TEAM construct completes execution by executing
25 its END TEAM statement.

26 A *codimension-decl* in a *coarray-association* associates a coarray with an established coarray during the execution
27 of the block. This coarray is an associating entity (8.1.3.2, 8.1.3.3, 16.5.1.6 of ISO/IEC 1539-1:2010). Its name is
28 an associate name that has the scope of the construct. It has the declared type, dynamic type, type parameters,
29 rank, and bounds of the established coarray. Its corank and cobounds are those specified in the *codimension-decl*.

30 Within a CHANGE TEAM construct, a coarray that is not an associating entity has the corank and cobounds
31 that it had when it was established.

32 An allocatable coarray that was allocated when execution of a CHANGE TEAM construct began shall not be
33 deallocated during execution of the construct. An allocatable coarray that is allocated when execution of a
34 CHANGE TEAM construct completes is deallocated if it was not allocated when execution of the construct
35 began.

36 The CHANGE TEAM and END TEAM statements are image control statements. All active images of the current
37 team shall execute the same CHANGE TEAM statement. When a CHANGE TEAM statement is executed, there
38 is an implicit synchronization of all active images of the team containing the executing image that is identified
39 by *team-variable*. On each active image of the team, execution of the segment following the statement is delayed
40 until all other active images of the team have executed the same statement the same number of times since
41 execution last began in the team that was current before execution of the CHANGE TEAM statement. When a
42 CHANGE TEAM construct completes execution, there is an implicit synchronization of all active images in the
43 current team. On each active image of the team, execution of the segment following the END TEAM statement
44 is delayed until all other active images of the team have executed the same construct the same number of times
45 since execution last began in the team that was current before execution of the corresponding CHANGE TEAM

1 statement.

NOTE 5.1

Deallocation of an allocatable coarray that was not allocated at the beginning of a CHANGE TEAM construct, but is allocated at the end of execution of the construct, occurs even for allocatable coarrays with the SAVE attribute.

2 5.4 Image selectors

3 The syntax rule R624 *image-selector* in subclause 6.6 of ISO/IEC 1539-1:2010 is replaced by:

4 R624 *image-selector* is *lbracket cosubscript-list* ■
5 ■ [*team-identifier*] [, STAT = *stat-variable*] *rbracket*

6 R624a *team-identifier* is TEAM_ID = *scalar-int-expr*
7 or TEAM = *team-variable*

8 C509 (R624) *stat-variable* shall not be a coindexed object.

9 If TEAM= appears in a coarray designator, *team-variable* shall be defined with a value that represents the
10 current or an ancestor team. The coarray shall be established in that team or an ancestor of that team and the
11 cosubscripts determine an image index in that team.

12 If TEAM_ID = appears in a coarray designator and the current team is not the initial team, the *scalar-int-expr*
13 shall be defined with the value of a team identifier for one of the teams that were formed by execution of the
14 FORM TEAM statement for the current team. The coarray shall be established in an ancestor of the current
15 team and the cosubscripts determine an image index in the team identified by TEAM_ID. If TEAM_ID= appears
16 in a coarray designator and the current team is the initial team, the value of *scalar-int-expr* is ignored.

NOTE 5.2

The image selector in `b[i]` identifies the current team. The image selector in `b[i,team_id=1]` identifies a sibling team. The image selector in `b[i,TEAM=ancestor]` identifies the team ancestor.

NOTE 5.3

The use of a STAT=specifier in an image selector allows a test to be made for a failed image in a reference where the use of a processor- dependent result could cause error termination or an incorrect execution path. Where there is no such possibility, it may be preferable to rely on the STAT=specifier in the next image control statement.

NOTE 5.4

In the following code, the vector *a* of length N*P is distributed over P images. Each image has an array A(0:N+1) holding its own values of *a* and halo values from its two neighbors. The images are divided into two teams that execute independently but periodically exchange halo data. Before the data exchange, all images (of the initial team) must be synchronized and for the data exchange the coindices of the initial team are needed.

```
USE, INTRINSIC :: ISO_FORTRAN_ENV, ONLY: TEAM_TYPE
TYPE(Team_Type) :: INITIAL, BLOCK
REAL :: A(0:N+1)[*]
INTEGER :: ME, P2
INITIAL = GET_TEAM()
ME = THIS_IMAGE()
P2 = NUM_IMAGES()/2
FORM TEAM(1+(ME-1)/P2,BLOCK)
CHANGE TEAM(BLOCK,B[*]=>A)
```

NOTE 5.4 (cont.)

```

DO
  ! Iterate within team
  :
  ! Halo exchange across team boundary
  SYNC TEAM(INITIAL)
  IF(ME==P2 ) B(N+1) = A(1) [ME+1,TEAM=INITIAL]
  IF(ME==P2+1) B(0) = A(N) [ME-1,TEAM=INITIAL]
  SYNC TEAM(INITIAL)
END DO
END TEAM

```

1 **5.5 FORM TEAM statement**

2 R506 *form-team-stmt* is FORM TEAM (*team-id*, *team-variable* ■
3 ■ [, *form-team-spec-list*])

4 R507 *team-id* is *scalar-int-expr*

5 R508 *form-team-spec* is NEW_INDEX = *scalar-int-expr*
6 or *sync-stat*

7 C510 (R506) No specifier shall appear more than once in a *form-team-spec-list*.

8 The FORM TEAM statement defines *team-variable* for a new team. The value of *team-id* specifies the new team
9 to which the executing image will belong. The value of *team-id* shall be positive and is the same for all images
10 that are members of the same team.

11 The value of the *scalar-int-expr* in a NEW_INDEX= specifier specifies the image index that the executing image
12 will have in the team specified by *team-id*. It shall be positive and less than or equal to the number of images
13 in the team. Each image with the same value for *team-id* shall have a different value for the NEW_INDEX=
14 specifier. If the NEW_INDEX= specifier does not appear, the image index that the executing image will have
15 in the team specified by *team-id* is a processor-dependent value that shall be positive and not greater than the
16 number of images in the team.

17 The FORM TEAM statement is an image control statement. If the FORM TEAM statement is executed on one
18 image, the same statement shall be executed on all active images of the current team. When a FORM TEAM
19 statement is executed, there is an implicit synchronization of all active images in the current team. On these
20 images, execution of the segment following the statement is delayed until all other active images in the current
21 team have executed the same statement the same number of times since execution last began in this team. If an
22 error condition other than detection of a failed image occurs, the team variable becomes undefined.

NOTE 5.5

Executing the statement

```
FORM TEAM ( 2-MOD(ME,2), ODD_EVEN )
```

with ME an integer with value THIS_IMAGE() and ODD_EVEN of type TEAM.TYPE, divides the current team into two teams according to whether the image index is even or odd.

NOTE 5.6

When executing on P^2 images with corresponding coarrays on each image representing parts of a larger array spread over a P by P square, the following code establishes teams for the rows with image indices equal to the column indices.

NOTE 5.6 (cont.)

```
USE, INTRINSIC :: ISO_FORTRAN_ENV
TYPE(Team_Type) :: Row
REAL :: A[P,*]
INTEGER :: ME(2)
ME(:) = THIS_IMAGE(A)
FORM TEAM(ME(1),ROW,NEW_INDEX=ME(2))
```

5.6 SYNC TEAM statement

1
2 R509 *sync-team-stmt* is SYNC TEAM (*team-variable* [, *sync-stat-list*])

3 The SYNC TEAM statement is an image control statement. The values of the *team-variables* on the active
4 images of the team shall be those defined by execution of the same FORM TEAM statement on all active images
5 of the team or shall be the values of team variables for the initial team. Execution of a SYNC TEAM statement
6 performs a synchronization of the executing image with each of the other active images of the team specified by
7 *team-variable*. Execution on an image, M, of the segment following the SYNC TEAM statement is delayed until
8 each active other image of the specified team has executed a SYNC TEAM statement specifying the same team
9 as many times as has image M since execution last began in this team. The segments that executed before the
10 SYNC TEAM statement on an image precede the segments that execute after the SYNC TEAM statement on
11 another image.

NOTE 5.7

A SYNC TEAM statement performs a synchronization of images of a particular team whereas a SYNC ALL statement performs a synchronization of all images of the current team.

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6 Failed images

6.1 Introduction

A failed image is one for which references or definitions of a variable on the image fail when that variable should be accessible; or an image that is not a stopped image and fails to respond during the execution of an image control statement or a reference to a collective subroutine. A failed image remains failed for the remainder of the program execution. The conditions that cause an image to fail are processor dependent.

Defining a coindexed object on a failed image has no effect other than defining the *stat-variable*, if one appears, with the value `STAT_FAILED_IMAGE` (6.4). The value of an expression that includes a reference to a coindexed object on a failed image is processor dependent. Execution continues after such a reference.

When an image fails during the execution of a segment, a data object on a non-failed image becomes undefined if it might be defined or undefined by execution of a statement of the segment other than an invocation of an atomic subroutine.

If the *lock-variable* in a `LOCK` statement was locked by a failed image and was not unlocked by that image, it becomes unlocked.

The `CRITICAL` statement described in subclause 8.1.5 of ISO/IEC 1539-1:2010 is extended as described in 6.3.

NOTE 6.1

A failed image is usually associated with a hardware failure of a cpu, memory system, or interconnection network. A failure that occurs while a coindexed reference or definition, or collective action, is in progress might leave variables on other images that would be defined by that action in an undefined state. Similarly, failure while using a file might leave that file in an undefined state.

NOTE 6.2

Continued execution after the failure of image 1 in the initial team might be difficult because of the lost connection to standard input. However, the likelihood of a given image failing is small. With a large number of images, the likelihood of some image other than image 1 in the initial team failing is significant and it is for this circumstance that `STAT_FAILED_IMAGE` is designed.

NOTE 6.3

In addition to detecting that an image has failed by having the variable in a `STAT=specifier` or a `STAT` argument of a call to a collective or atomic subroutine assigned the value `STAT_FAILED_IMAGE`, an image can get the indices of failed images in a specified team by invoking the intrinsic function `FAILED_IMAGES`.

6.2 FAIL IMAGE statement

R601 *fail-image-stmt* is FAIL IMAGE

Execution of a `FAIL IMAGE` statement causes the executing image to behave as if it has failed. Neither normal nor error termination is initiated, but no further statements are executed by that image.

NOTE 6.4

The `FAIL IMAGE` statement allows a program to test a recovery algorithm without experiencing an actual failure.

NOTE 6.4 (cont.)

On a processor that does not have the ability to detect that an image has failed, execution of a FAIL IMAGE statement might provide a simulated failure environment that provides debug information.

In a piece of code that executes about once a second, invoking this subroutine on an image

```

SUBROUTINE FAIL
  REAL :: X
  CALL RANDOM_NUMBER(X)
  IF (X<0.001) FAIL IMAGE
END SUBROUTINE FAIL

```

will cause that image to have an independent 1/1000 chance of failure every second if the random number generators on different images are independent.

1 6.3 CRITICAL construct

2 The syntax rule R811 in subclause 8.1.5 of ISO/IEC 1539-1:2010 is replaced by:

3 R811 *critical-stmt* is [*critical-construct-name* :] CRITICAL [(*sync-stat-list*)]

4 If an image fails during the execution of a CRITICAL construct, the execution of the construct is regarded
 5 by other images as complete. If the CRITICAL statement of a CRITICAL construct has a STAT= specifier,
 6 and an image fails while executing that construct, the specified variable will become defined with the value
 7 STAT_FAILED_IMAGE on the next image to execute the construct.

8 6.4 STAT_FAILED_IMAGE

9 If the processor has the ability to detect that an image has failed, the value of the default integer scalar constant
 10 STAT_FAILED_IMAGE is positive; otherwise, the value of STAT_FAILED_IMAGE is negative. If the processor
 11 has the ability to detect that an image involved in execution of an image control statement, a reference to a
 12 coindexed object, or a collective or atomic subroutine has failed and does so, and no error condition other than
 13 a failed image image is detected, the value of STAT_FAILED_IMAGE is assigned to the variable specified in a
 14 STAT=specifier in an execution of an image control statement or a reference to a coindexed object, or the STAT
 15 argument in an invocation of a collective or atomic procedure. If more than one nonzero status value is valid for
 16 the execution of a statement, the status variable is defined with a value other than STAT_FAILED_IMAGE. If
 17 the STAT= specifier of an execution of a CHANGE TEAM, END TEAM, FORM TEAM, SYNC ALL, SYNC
 18 IMAGES, or SYNC TEAM statement is assigned the value STAT_FAILED_IMAGE, the intended action shall
 19 have taken place for all active images involved.

20 STAT_FAILED_IMAGE is defined in the intrinsic module ISO_FORTRAN_ENV. The values of the named
 21 constants IOSTAT_INQUIRE_INTERNAL_UNIT, STAT_FAILED_IMAGE, STAT_LOCKED, STAT_LOCKED_
 22 OTHER_IMAGE, STAT_STOPPED_IMAGE, and STAT_UNLOCKED shall be distinct.

7 Events

7.1 Introduction

An image can post an event to notify another image that it can proceed to work on tasks that use common resources. An image can wait on events posted by other images and can query if images have posted events.

7.2 EVENT_TYPE

EVENT_TYPE is a derived type with private components. It is an extensible type with no type parameters. Each component is fully default initialized. EVENT_TYPE is defined in the intrinsic module ISO_FORTRAN_ENV.

A scalar variable of type EVENT_TYPE is an event variable. An event variable has a count that is updated by execution of a sequence of EVENT POST or EVENT WAIT statements. The effect of each change is as if the atomic subroutine ATOMIC_ADD were executed with a variable that stores the event count as its ATOM argument. A coarray that is of type EVENT_TYPE may be referenced or defined during the execution of a segment that is unordered relative to the execution of another segment in which that coarray of type EVENT_TYPE is defined. The event count is type integer with kind ATOMIC_INT_KIND, where ATOMIC_INT_KIND is a named constant defined in the intrinsic module ISO_FORTRAN_ENV. The initial value of the event count of an event variable is zero.

C701 A named variable of type EVENT_TYPE shall be a coarray. A named variable with a noncoarray subcomponent of type EVENT_TYPE shall be a coarray.

C702 An event variable shall not appear in a variable definition context except as the *event-variable* in an EVENT POST or EVENT WAIT statement, as an *allocate-object* in an ALLOCATE statement without a SOURCE= *alloc-opt*, as an *allocate-object* in a DEALLOCATE statement, or as an actual argument in a reference to a procedure with an explicit interface if the corresponding dummy argument has INTENT (INOUT).

C703 A variable with a nonpointer subobject of type EVENT_TYPE shall not appear in a variable definition context except as an *allocate-object* in an ALLOCATE statement without a SOURCE= *alloc-opt*, as an *allocate-object* in a DEALLOCATE statement, or as an actual argument in a reference to a procedure with an explicit interface if the corresponding dummy argument has INTENT (INOUT).

NOTE 7.1

The restrictions against changing an event variable except via EVENT POST and EVENT WAIT statements ensure the integrity of its value and facilitate efficient implementation, particularly when special synchronization is needed for correct event handling.

7.3 EVENT POST statement

The EVENT POST statement provides a way to post an event. It is an image control statement.

R701 *event-post-stmt* is EVENT POST (*event-variable* [, *sync-stat-list*])

R702 *event-variable* is *scalar-variable*

C704 (R702) An *event-variable* shall be of type EVENT_TYPE (7.2).

Successful execution of an EVENT POST statement atomically increments the count of the event variable by 1.

1 If an error condition occurs during execution of an EVENT POST statement, the count does not change.

2 If the segment that precedes an EVENT POST statement is unordered with respect to the segment that precedes
3 another EVENT POST statement for the same event variable, the order of execution of the EVENT POST
4 statements is processor dependent.

NOTE 7.2

It is expected that an image will continue executing after posting an event without waiting for an EVENT WAIT statement to execute on the image of the event variable.

5 7.4 EVENT WAIT statement

6 The EVENT WAIT statement provides a way to wait until events are posted. It is an image control statement.

7 R703 *event-wait-stmt* is EVENT WAIT (*event-variable* [, *wait-spec-list*])

8 R704 *wait-spec* is *until-spec*
9 or *sync-stat*

10 R705 *until-spec* is UNTIL_COUNT = *scalar-int-expr*
11

12 C705 (R703) An *event-variable* in an *event-wait-stmt* shall not be coindexed.

13 C706 (R703) An *until-spec* shall not appear more than once in an *event-wait-stmt*.

14 Execution of an EVENT WAIT statement causes the following sequence of actions:

- 15 (1) the threshold value is set to *scalar-int-expr* if the UNTIL_COUNT specifier appears and *scalar-int-*
16 *expr* has a positive value, and to 1 otherwise,
- 17 (2) the executing image waits until the count of the event variable is greater than or equal to its threshold
18 value or an error condition occurs, and
- 19 (3) if no error condition occurs, the count of the event variable is atomically decremented by its threshold
20 value.

21 If an EVENT WAIT statement using an event variable is executed with a threshold of k , the segments preceding
22 at least k EVENT POST statements using that event variable will precede the segment following the EVENT
23 WAIT statement. The segment following a different EVENT WAIT statement using the same event variable can
24 be ordered to succeed segments preceding other EVENT POST statements using that event variable.

25 A failed image might cause an error condition for an EVENT WAIT statement.

NOTE 7.3

An unreasonably long wait on an EVENT WAIT statement in the presence of failed images may be because it was intended that the event be posted by an image that has failed.

NOTE 7.4

The segment that follows the execution of an EVENT WAIT statement is ordered with respect to all segments that precede EVENT POST statements that caused prior changes in the sequence of values of the event variable.

NOTE 7.5

Event variables of type EVENT_TYPE are restricted so that EVENT WAIT statements can only wait on an event variable on the executing image. This enables more efficient implementation of this concept.

8 Intrinsic procedures

8.1 General

Detailed specifications of the generic intrinsic procedures `ATOMIC_ADD`, `ATOMIC_AND`, `ATOMIC_CAS`, `ATOMIC_FETCH_ADD`, `ATOMIC_FETCH_AND`, `ATOMIC_FETCH_OR`, `ATOMIC_FETCH_XOR`, `ATOMIC_OR`, `ATOMIC_XOR`, `CO_BROADCAST`, `CO_MAX`, `CO_MIN`, `CO_REDUCE`, `CO_SUM`, `EVENT_QUERY`, `FAILED_IMAGES`, `GET_TEAM`, `IMAGE_STATUS`, `STOPPED_IMAGES`, and `TEAM_ID` are provided in 8.4. The types and type parameters of the arguments to these intrinsic procedures are determined by these specifications. The “Argument” paragraphs specify requirements on the [actual arguments](#) of the procedures. All of these intrinsic procedures are pure.

The intrinsic procedures `ATOMIC_DEFINE`, `ATOMIC_REF`, `IMAGE_INDEX`, `MOVE_ALLOC`, `NUM_IMAGES`, and `THIS_IMAGE` described in clause 13 of ISO/IEC 1539-1:2010, as modified by ISO/IEC 1539-1:2010/Cor 1:2012, are extended as described in 8.5.

8.2 Atomic subroutines

An atomic subroutine is an intrinsic subroutine that performs an action on its `ATOM` argument or the count of its `EVENT` argument atomically. For any two executions of atomic subroutines in unordered segments by different images on the same atomic object, the effect is as if one of the executions is performed before the other in a single segment on a separate image, without access to the object in either execution interleaving with access to the object in the other. Which is executed first is indeterminate. The sequence of atomic actions within ordered segments is specified in 2.3.5 of ISO/IEC 1539-1:2010. If two variables are updated by atomic actions in segments P_1 and P_2 , and the changes to them are observed by atomic accesses from a segment Q which is unordered relative to either P_1 or P_2 , the changes need not be observed in segment Q in the same order as they are made in segments P_1 and P_2 , even if segments P_1 and P_2 are ordered.

For invocation of an atomic subroutine with an argument `OLD`, the determination of the value to be assigned to `OLD` is part of the atomic operation even though the assignment of that value to `OLD` is not. For invocation of an atomic subroutine, evaluation of an `INTENT(IN)` argument is not part of the atomic action.

If the `STAT` argument is present in an invocation of an atomic subroutine and no error condition occurs, the argument is assigned the value zero.

If the `STAT` argument is present in an invocation of an atomic subroutine other than `ATOMIC_REF` and an error condition occurs, any `ATOM` or `OLD` argument becomes undefined. The `STAT` argument is assigned the value `STAT_FAILED_IMAGE` if a coindexed `ATOM` or `EVENT` argument is determined to be located on a failed image; otherwise, the `STAT` argument is assigned a processor-dependent positive value that is different from `STAT_FAILED_IMAGE`.

If a condition occurs that would assign a nonzero value to a `STAT` argument but the `STAT` argument is not present, error termination is initiated.

NOTE 8.1

The properties of atomic subroutines support their use for designing customized synchronization mechanisms. The programmer needs to account for all possible orderings of sequences of atomic subroutine executions that can arise as a consequence of the above rules; the orderings can turn out to be different on different images even in the same program run.

8.3 Collective subroutines

A collective subroutine is one that is invoked on each active image of the current team to perform a calculation on those images and that assigns the computed value on one or all of them. If it is invoked by one image, it shall be invoked by the same statement on all active images of the current team in execution segments that are not ordered with respect to each other. From the beginning to the end of execution as the current team, the sequence of invocations of collective subroutines shall be the same on all active images of the current team. A call to a collective subroutine shall appear only in a context that allows an image control statement.

If the A argument to a collective subroutine is a whole coarray the corresponding ultimate arguments on all active images of the current team shall be corresponding coarrays as described in 2.4.7 of ISO/IEC 1539-1:2010.

Collective subroutines have the optional arguments STAT and ERRMSG. If the STAT argument is present in the invocation on one image it shall be present on the corresponding invocations on all active images of the current team.

If the STAT argument is present in an invocation of a collective subroutine and its execution is successful, the argument is assigned the value zero.

If the STAT argument is present in an invocation of a collective subroutine and an error condition occurs, the argument is assigned a nonzero value and the A argument becomes undefined. If execution involves synchronization with an image that has initiated normal termination, the argument is assigned the value of STAT_STOPPED_IMAGE in the intrinsic module ISO_FORTRAN_ENV; otherwise, if all images of the current team are active, the argument is assigned a processor-dependent positive value that is different from the value of STAT_STOPPED_IMAGE or STAT_FAILED_IMAGE in the intrinsic module ISO_FORTRAN_ENV. Otherwise, if an image of the current team has been detected as failed, the argument is assigned the value of the constant STAT_FAILED_IMAGE.

If a condition occurs that would assign a nonzero value to a STAT argument but the STAT argument is not present, error termination is initiated.

If an ERRMSG argument is present in an invocation of a collective subroutine and an error condition occurs during its execution, the processor shall assign an explanatory message to the argument. If no error condition occurs, the processor shall not change the value of the argument.

NOTE 8.2

The argument A becomes undefined if an error condition occurs during execution of a collective subroutine because it is intended that implementations be able to use A as scratch space.

NOTE 8.3

All of the collective subroutines have an argument A with INTENT(INOUT) that holds the original data on entry and the result on return. If it is desired to retain the original data, this is readily obtained by making a copy before entry. Here is an example:

```
REDUCTION = ORIGINAL
CALL CO_MIN(REDUCTION)
```

NOTE 8.4

There is no separate synchronization at the beginning and end of an invocation of a collective subroutine, which allows overlap with other actions. However, each collective subroutine involves transfer of data between images. A transfer from an image cannot occur before the collective subroutine has been invoked on that image. The rules of Fortran do not allow the value of an associated argument such as A to be changed except via the argument. This includes action taken by another image that has not started its execution of the collective subroutine or has finished it. This restriction has the effect of a partial synchronization of invocations of a collective subroutine.

8.4 New intrinsic procedures

8.4.1 ATOMIC_ADD (ATOM, VALUE [, STAT])

Description. Atomic add operation.

Class. Atomic subroutine.

Arguments.

ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an INTENT (INOUT) argument. ATOM becomes defined with the value of ATOM + INT(VALUE, ATOMIC_INT_KIND).

VALUE shall be an integer scalar. It is an INTENT (IN) argument.

STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an INTENT(OUT) argument.

Example.

CALL ATOMIC_ADD(I[3], 42) causes the value of I on image 3 to become defined with the value 46 if the value of I[3] was 4 when the atomic operation executed.

8.4.2 ATOMIC_AND (ATOM, VALUE [, STAT])

Description. Atomic bitwise AND operation.

Class. Atomic subroutine.

Arguments.

ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an INTENT (INOUT) argument. ATOM becomes defined with the value IAND (ATOM, INT(VALUE, ATOMIC_INT_KIND)).

VALUE shall be an integer scalar. It is an INTENT(IN) argument.

STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an INTENT(OUT) argument.

Example. CALL ATOMIC_AND (I[3], 6) causes I on image 3 to become defined with the value 4 if the value of I[3] was 5 when the atomic operation executed.

8.4.3 ATOMIC_CAS (ATOM, OLD, COMPARE, NEW [, STAT])

Description. Atomic compare and swap.

Class. Atomic subroutine.

Arguments.

ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND or of type logical with kind ATOMIC_LOGICAL_KIND, where ATOMIC_INT_KIND and ATOMIC_LOGICAL_KIND are named constants in the intrinsic module ISO_FORTRAN_ENV. It is an INTENT (INOUT) argument. If the value of ATOM is equal to the value of COMPARE, ATOM becomes defined with the value of INT (NEW, ATOMIC_INT_KIND) if it is of type integer, and with the value of NEW if it is of type logical. If the value of ATOM is not equal to the value of COMPARE, the value of ATOM is not changed.

OLD shall be a scalar of the same type and kind as ATOM. It is an INTENT (OUT) argument. It is

1 defined with the value of ATOM that was used for performing the atomic operation.
2 COMPARE shall be a scalar of the same type and kind as ATOM. It is an INTENT(IN) argument.
3 NEW shall be a scalar of the same type as ATOM. It is an INTENT(IN) argument.
4 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
5 INTENT(OUT) argument.

6 **Example.** CALL ATOMIC_CAS(I[3], OLD, Z, 1) causes I on image 3 to become defined with the value 1 if its
7 value is that of Z, and OLD to be defined with the value of I on image 3 that was used for performing the atomic
8 operation.

9 **8.4.4 ATOMIC_FETCH_ADD (ATOM, VALUE, OLD [, STAT])**

10 **Description.** Atomic fetch and add operation.

11 **Class.** Atomic subroutine.

12 **Arguments.**

13 ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where
14 ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an
15 INTENT (INOUT) argument. ATOM becomes defined with the value of ATOM + INT(VALUE,
16 ATOMIC_INT_KIND).

17 VALUE shall be an integer scalar. It is an INTENT (IN) argument.

18 OLD shall be a scalar of the same type and kind as ATOM. It is an INTENT (OUT) argument. It is
19 defined with the value of ATOM that was used for performing the atomic operation.

20 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
21 INTENT(OUT) argument.

22 **Example.** CALL ATOMIC_FETCH_ADD(I[3], 7, OLD) causes I on image 3 to become defined with the value
23 12 and the value of OLD on the image executing the statement to be defined with the value 5 if the value of I[3]
24 was 5 when the atomic operation executed.

25 **8.4.5 ATOMIC_FETCH_AND (ATOM, VALUE, OLD [, STAT])**

26 **Description.** Atomic fetch and bitwise AND operation.

27 **Class.** Atomic subroutine.

28 **Arguments.**

29 ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where
30 ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an IN-
31 TENT (INOUT) argument. ATOM becomes defined with the value of IAND(ATOM, INT(VALUE,
32 ATOMIC_INT_KIND)).

33 VALUE shall be an integer scalar. It is an INTENT (IN) argument.

34 OLD shall be a scalar of the same type and kind as ATOM. It is an INTENT (OUT) argument. It is
35 defined with the value of ATOM that was used for performing the atomic operation.

36 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
37 INTENT(OUT) argument.

38 **Example.** CALL ATOMIC_FETCH_AND (I[3], 6, IOLD) causes I on image 3 to become defined with the value
39 4 and the value of IOLD on the image executing the statement to be defined with the value 5 if the value of I[3]
40 was 5 when the atomic operation executed.

8.4.6 ATOMIC_FETCH_OR (ATOM, VALUE, OLD [, STAT])

Description. Atomic fetch and bitwise OR operation.

Class. Atomic subroutine.

Arguments.

ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an INTENT (INOUT) argument. ATOM becomes defined with the value of IOR(ATOM, INT(VALUE, ATOMIC_INT_KIND)).

VALUE shall be an integer scalar. It is an INTENT (IN) argument.

OLD shall be a scalar of the same type and kind as ATOM. It is an INTENT (OUT) argument. It is defined with the value of ATOM that was used for performing the atomic operation.

STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an INTENT(OUT) argument.

Example. CALL ATOMIC_FETCH_OR (I[3], 1, IOLD) causes I on image 3 to become defined with the value 3 and the value of IOLD on the image executing the statement to be defined with the value 2 if the value of I[3] was 2 when the atomic operation executed.

8.4.7 ATOMIC_FETCH_XOR (ATOM, VALUE, OLD [, STAT])

Description. Atomic fetch and bitwise exclusive OR operation.

Class. Atomic subroutine.

Arguments.

ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an INTENT (INOUT) argument. ATOM becomes defined with the value of IEXOR(ATOM, INT(VALUE, ATOMIC_INT_KIND)).

VALUE shall be an integer scalar. It is an INTENT (IN) argument.

OLD shall be a scalar of the same type and kind as ATOM. It is an INTENT (OUT) argument. It is defined with the value of ATOM that was used for performing the atomic operation.

STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an INTENT(OUT) argument.

Example. CALL ATOMIC_FETCH_XOR (I[3], 1, IOLD) causes I on image 3 to become defined with the value 2 and the value of IOLD on the image executing the statement to be defined with the value 3 if the value of I[3] was 3 when the atomic operation executed.

8.4.8 ATOMIC_OR (ATOM, VALUE [, STAT])

Description. Atomic bitwise OR operation.

Class. Atomic subroutine.

Arguments.

ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an INTENT (INOUT) argument. ATOM becomes defined with the value IOR (ATOM, INT(VALUE, ATOMIC_INT_KIND)).

VALUE shall be an integer scalar. It is an INTENT (IN) argument.

1 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
2 INTENT(OUT) argument.

3 **Example.** CALL ATOMIC_OR (I[3], 1) causes I on image 3 to become defined with the value 3 if the value of
4 I[3] was 2 when the atomic operation executed.

5 **8.4.9 ATOMIC_XOR (ATOM, VALUE [, STAT])**

6 **Description.** Atomic bitwise exclusive OR operation.

7 **Class.** Atomic subroutine.

8 **Arguments.**

9 ATOM shall be a scalar coarray or coindexed object of type integer with kind ATOMIC_INT_KIND, where
10 ATOMIC_INT_KIND is a named constant in the intrinsic module ISO_FORTRAN_ENV. It is an
11 INTENT (INOUT) argument. ATOM becomes defined with the value IEOR (ATOM, INT(VALUE,
12 ATOMIC_INT_KIND)).

13 VALUE shall be an integer scalar. It is an INTENT (IN) argument.

14 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
15 INTENT(OUT) argument.

16 **Example.** CALL ATOMIC_XOR (I[3], 1) causes I on image 3 to become defined with the value 2 if the value of
17 I[3] was 3 when the atomic operation executed.

18 **8.4.10 CO_BROADCAST (A, SOURCE_IMAGE [, STAT, ERRMSG])**

19 **Description.** Copy a value to all images of the current team.

20 **Class.** Collective subroutine.

21 **Arguments.**

22 A shall have the same dynamic type and type parameter values on all images in the current team. It
23 shall not be a coindexed object. It is an INTENT(INOUT) argument. If it is an array, it shall have
24 the same shape on all images in the current team. A becomes defined, as if by intrinsic assignment,
25 on all images in the current team with the value of A on image SOURCE_IMAGE.

26 SOURCE_IMAGE shall be an integer scalar. It is an INTENT(IN) argument. It shall be the image index of an
27 image in the current team and have the same value on all images in the current team.

28 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
29 INTENT(OUT) argument.

30 ERRMSG (optional) shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

31 The effect of the presence of the optional arguments STAT and ERRMSG is described in [8.3](#).

32 **Example.** If A is the array [1, 5, 3] on image one, after execution of CALL CO_BROADCAST(A,1) the value
33 of A on all images of the current team is [1, 5, 3].

34 **8.4.11 CO_MAX (A [, RESULT_IMAGE, STAT, ERRMSG])**

35 **Description.** Compute elemental maximum value on the current team of images.

36 **Class.** Collective subroutine.

37 **Arguments.**

38 A shall be of type integer, real, or character. It shall have the same type and type parameters on
39 all images in the current team. It shall not be a coindexed object. It is an INTENT(INOUT)

argument. If it is a scalar, the computed value is equal to the maximum value of A on all images in the current team. If it is an array it shall have the same shape on all images of the current team and each element of the computed value is equal to the maximum value of all corresponding elements of A on the images in the current team.

RESULT_IMAGE (optional) shall be an integer scalar. It is an INTENT(IN) argument. If it is present, it shall be present on all images in the current team, have the same value on all images in the current team, and that value shall be the image index of an image in the current team.

STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an INTENT(OUT) argument.

ERRMSG (optional) shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

If RESULT_IMAGE is not present, the computed value is assigned to A on all images in the current team. If RESULT_IMAGE is present, the computed value is assigned to A on image RESULT_IMAGE and A on all other images in the current team becomes undefined.

The effect of the presence of the optional arguments STAT and ERRMSG is described in 8.3.

Example. If the number of images in the current team is two and A is the array [1, 5, 3] on one image and [4, 1, 6] on the other image, the value of A after executing the statement CALL CO_MAX(A) is [4, 5, 6] on both images.

8.4.12 CO_MIN (A [, RESULT_IMAGE, STAT, ERRMSG])

Description. Compute elemental minimum value on the current team of images.

Class. Collective subroutine.

Arguments.

A shall be of type integer, real, or character. It shall have the same type and type parameters on all images in the current team. It shall not be a coindexed object. It is an INTENT(INOUT) argument. If it is a scalar, the computed value is equal to the minimum value of A on all images in the current team. If it is an array it shall have the same shape on all images in the current team and each element of the computed value is equal to the minimum value of all corresponding elements of A on the images in the current team.

RESULT_IMAGE (optional) shall be an integer scalar. It is an INTENT(IN) argument. If it is present, it shall be present on all images in the current team, have the same value on all images in the current team, and that value shall be the image index of an image in the current team.

STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an INTENT(OUT) argument.

ERRMSG (optional) shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

If RESULT_IMAGE is not present, the computed value is assigned to A on all images in the current team. If RESULT_IMAGE is present, the computed value is assigned to A on image RESULT_IMAGE and A on all other images in the current team becomes undefined.

The effect of the presence of the optional arguments STAT and ERRMSG is described in 8.3.

Example. If the number of images in the current team is two and A is the array [1, 5, 3] on one image and [4, 1, 6] on the other image, the value of A after executing the statement CALL CO_MIN(A) is [1, 1, 3] on both images.

8.4.13 CO_REDUCE (A, OPERATOR [, RESULT_IMAGE, STAT, ERRMSG])

Description. General reduction of elements on the current team of images.

1 **Class.** Collective subroutine.

2 **Arguments.**

3 A shall not be polymorphic. It shall have the same type and type parameters on all images in the
4 current team. It shall not be a coindexed object. It is an INTENT(INOUT) argument. If A is a
5 scalar, the computed value is the result of the reduction operation of applying OPERATOR to the
6 values of A on all images in the current team. If A is an array it shall have the same shape on all
7 images in the current team and each element of the computed value is equal to the result of the
8 reduction operation of applying OPERATOR to all corresponding elements of A on all images in
9 the current team.

10 OPERATOR shall be a pure function with two scalar, nonallocatable, nonpointer, nonoptional arguments of the
11 same type and type parameters as A. Its result shall have the same type and type parameters as A.
12 The arguments and result shall not be polymorphic. If one argument has the ASYNCHRONOUS,
13 TARGET, or VALUE attribute, both shall have the attribute. OPERATOR shall implement a
14 mathematically commutative and associative operation. OPERATOR shall be the same function
15 on all images in the current team.

16 RESULT_IMAGE (optional) shall be an integer scalar. It is an INTENT(IN) argument. If it is present, it shall
17 be present on all images in the current team, have the same value on all images in the current team,
18 and that value shall be the image index of an image in the current team.

19 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
20 INTENT(OUT) argument.

21 ERRMSG (optional) shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

22 If RESULT_IMAGE is not present, the computed value is assigned to A as if by intrinsic assignment on all
23 images in the current team. If RESULT_IMAGE is present, the computed value is assigned to A as if by intrinsic
24 assignment on image RESULT_IMAGE and A on all other images in the current team becomes undefined.

25 The computed value of a reduction operation over a set of values is the result of an iterative process. Each
26 iteration involves the evaluation of OPERATOR(x,y) for x and y in the set, the removal of x and y from the set, and
27 the addition of the value of OPERATOR(x,y) to the set. The process terminates when the set has only one element
28 which is the value of the reduction.

29 The effect of the presence of the optional arguments STAT and ERRMSG is described in 8.3.

30 **Example.** If the number of images in the current team is two and A is the array [1, 5, 3] on one image and [4,
31 1, 6] on the other image, and MyADD is a function that returns the sum of its two integer arguments, the value
32 of A after executing the statement CALL CO_REDUCE(A, MyADD) is [5, 6, 9] on both images.

33 8.4.14 CO_SUM (A [, RESULT_IMAGE, STAT, ERRMSG])

34 **Description.** Sum elements on the current team of images.

35 **Class.** Collective subroutine.

36 **Arguments.**

37 A shall be of numeric type. It shall have the same type and type parameters on all images in the
38 current team. It shall not be a coindexed object. It is an INTENT(INOUT) argument. If it is a
39 scalar, the computed value is equal to a processor-dependent and image-dependent approximation
40 to the sum of the values of A on all images in the current team. If it is an array it shall have the
41 same shape on all images in the current team and each element of the computed value is equal to a
42 processor-dependent and image-dependent approximation to the sum of all corresponding elements
43 of A on the images in the current team.

44 RESULT_IMAGE (optional) shall be an integer scalar. It is an INTENT(IN) argument. If it is present, it shall
45 be present on all images in the current team, have the same value on all images in the current team,
46 and that value shall be the image index of an image in the current team.

1 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
2 INTENT(OUT) argument.

3 ERRMSG (optional) shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

4 If RESULT_IMAGE is not present, the computed value is assigned to A on all images in the current team. If
5 RESULT_IMAGE is present, the computed value is assigned to A on image RESULT_IMAGE and A on all other
6 images in the current team becomes undefined.

7 The effect of the presence of the optional arguments STAT and ERRMSG is described in 8.3.

8 **Example.** If the number of images in the current team is two and A is the array [1, 5, 3] on one image and [4,
9 1, 6] on the other image, the value of A after executing the statement CALL CO_SUM(A) is [5, 6, 9] on both
10 images.

11 8.4.15 EVENT_QUERY (EVENT, COUNT [, STAT])

12 **Description.** Query the count of an event variable.

13 **Class.** Atomic subroutine.

14 **Arguments.**

15 EVENT shall be a scalar of type EVENT_TYPE defined in the intrinsic module ISO_FORTRAN_ENV. It is
16 an INTENT(IN) argument.

17 COUNT shall be an integer scalar with a decimal range no smaller than that of default integer. It is an
18 INTENT(OUT) argument. If no error conditions occurs, COUNT is assigned the value of the count
19 of EVENT. Otherwise, it is assigned the value 0.

20 STAT (optional) shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is an
21 INTENT(OUT) argument.

22 **Example.** If EVENT is an event variable for which there have been no successful posts or waits, after the
23 invocation

24 CALL EVENT_QUERY (EVENT, COUNT)

25 the integer variable COUNT has the value 0. If there have been 10 successful posts to EVENT[2] and 2 successful
26 waits without an UNTIL_COUNT specification, after the invocation

27 CALL EVENT_QUERY (EVENT[2], COUNT)

28 COUNT has the value 8.

NOTE 8.5

Execution of EVENT_QUERY does not imply any synchronization.

29 8.4.16 FAILED_IMAGES ([TEAM, KIND])

30 **Description.** Indices of failed images.

31 **Class.** Transformational function.

32 **Arguments.**

33 TEAM (optional) shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_ENV.
34 Its value shall represent the current or an ancestor team.

35 KIND (optional) shall be a scalar integer constant expression. Its value shall be the value of a kind type parameter
36 for type INTEGER. The decimal range for integers of this kind shall be at least as large as for default
37 integer.

1 **Result Characteristics.** Integer. If KIND is present, the kind type parameter is that specified by the value
 2 of KIND; otherwise, the kind type parameter is that of default integer type. The result is an array of rank one
 3 whose size is equal to the number of images in the specified team that are known by the invoking image to have
 4 failed.

5 **Result Value.** If TEAM is present, its value specifies the team; otherwise, the team specified is the current team.
 6 The elements of the result are the values of the image indices of the known failed images in the specified team, in
 7 numerically increasing order. If the executing image has previously executed an image control statement whose
 8 STAT= specifier assigned the value STAT_FAILED_IMAGE from the intrinsic module ISO_FORTRAN_ENV, or
 9 invoked a collective subroutine whose STAT argument was set to STAT_FAILED_IMAGE, and has not meanwhile
 10 entered or left a CHANGE TEAM construct, at least one image in the set of images participating in that image
 11 control statement or collective invocation shall be known to have failed.

12 **Examples.** If image 3 is the only image in the current team that is known by the invoking image to have failed,
 13 FAILED_IMAGES() has the value [3]. If there are no images in the current team that are known by the invoking
 14 image to have failed, FAILED_IMAGES() is a zero-sized array.

15 8.4.17 GET_TEAM ([LEVEL])

16 **Description.** Team value.

17 **Class.** Transformational function.

18 **Argument.** LEVEL (optional) shall be a scalar integer whose value shall be equal to one of the named constants
 19 INITIAL_TEAM, PARENT_TEAM, or CURRENT_TEAM defined in the intrinsic module ISO_FORTRAN_ENV.

20 **Result Characteristics.** Scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_ENV.

21 **Result Value.** The result is the value of a team variable for the current team if LEVEL is not present, LEVEL
 22 is present with the value CURRENT_TEAM, or the current team is the initial team. Otherwise, the result is the
 23 value of a team variable for the parent team if LEVEL is present with the value PARENT_TEAM, and for the
 24 initial team if LEVEL is present with the value INITIAL_TEAM.

25 **Examples.**

```

26     USE, INTRINSIC :: ISO_FORTRAN_ENV, ONLY: TEAM_TYPE
27     TYPE(Team_Type) :: World_Team, Team2
28
29     ! Define a team variable representing the initial team
30     World_Team = GET_TEAM()
31     END
32
33     SUBROUTINE TT (A)
34     USE, INTRINSIC :: ISO_FORTRAN_ENV, ONLY: TEAM_TYPE
35     REAL A[*]
36     TYPE(Team_Type) :: New_Team, Parent_Team
37
38     ... ! Form New_Team
39
40     Parent_Team = GET_TEAM()
41
42     CHANGE_TEAM(New_Team)
43
44     ! Reference image 1 in parent's team
45     A [1, TEAM=Parent_Team] = 4.2
46
47     ! Reference image 1 in current team
48     A [1] = 9.0

```

```

1     END TEAM
2     END SUBROUTINE TT
3

```

8.4.18 IMAGE_STATUS (IMAGE, [TEAM])

Description. Status of images.

Class. Elemental function.

Arguments.

IMAGE shall be of type integer.

TEAM (optional) shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_ENV. Its value shall represent the current or an ancestor team.

Result Characteristics. Default integer.

Result Value. If TEAM is present, its value specifies the team; otherwise, the team specified is the current team. The result value is STAT_FAILED_IMAGE if the specified image has failed, STAT_STOPPED_IMAGE if that image has initiated normal termination, a positive processor-dependent value different from STAT_FAILED_IMAGE or STAT_STOPPED_IMAGE if some other error has occurred for that image, and zero otherwise.

Example. If image 3 of the current team has failed, IMAGE_STATUS (3) has the value STAT_FAILED_IMAGE.

8.4.19 STOPPED_IMAGES ([TEAM, KIND])

Description. Indices of stopped images.

Class. Transformational function.

Arguments.

TEAM (optional) shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_ENV. Its value shall represent the current or an ancestor team.

KIND (optional) shall be a scalar integer constant expression. Its value shall be the value of a kind type parameter for type INTEGER. The decimal range for integers of this kind shall be at least as large as for default integer.

Result Characteristics. Integer. If KIND is present, the kind type parameter is that specified by the value of KIND; otherwise, the kind type parameter is that of default integer type. The result is an array of rank one whose size is equal to the number of images in the specified team that have initiated normal termination.

Result Value. If TEAM is present, its value specifies the team; otherwise, the team specified is the current team. The elements of the result are the values of the indices of the images that have initiated normal termination in the specified team, in numerically increasing order. If the executing image has previously executed an image control statement whose STAT= specifier assigned the value STAT_STOPPED_IMAGE from the intrinsic module ISO_FORTRAN_ENV or invoked a collective subroutine whose STAT argument was set to STAT_STOPPED_IMAGE, and has not meanwhile entered or left a CHANGE TEAM construct, at least one of the images participating in that image control statement or collective invocation shall have initiated normal termination.

Examples. If image 3 is the only image in the current team that has initiated normal termination, STOPPED_IMAGES() has the value [3]. If there are no images in the current team that have initiated normal termination, STOPPED_IMAGES() is a zero-sized array.

8.4.20 TEAM_ID ([TEAM])

Description. Team identifier.

1 **Class.** Transformational function.

2 **Argument.** TEAM (optional) shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO-
3 FORTRAN_ENV. Its value shall represent the current or an ancestor team.

4 **Result Characteristics.** Default integer scalar.

5 **Result Value.** If TEAM is present its value specifies the team; otherwise, the team specified is the current team.
6 If the specified team is the initial team, the result is -1; otherwise, the result value is the team identifier of the
7 invoking image in the specified team.

8 **Example.** The following code illustrates the use of TEAM_ID to control which code is executed.

```
9 TYPE(Team_Type) :: ODD_EVEN
10 :
11 ME = THIS_IMAGE()
12 FORM TEAM ( 2-MOD(ME,2), ODD_EVEN )
13 CHANGE TEAM (ODD_EVEN)
14   SELECT CASE (TEAM_ID())
15     CASE (1)
16       : ! Code for images with odd image indices in parent team
17     CASE (2)
18       : ! Code for images with even image indices in parent team
19   END SELECT
20 END TEAM
```

21 8.5 Modified intrinsic procedures

22 8.5.1 ATOMIC_DEFINE and ATOMIC_REF

23 The intrinsic subroutines ATOMIC_DEFINE and ATOMIC_REF in ISO/IEC 1539-1:2010 are modified to take
24 account of the possibility that an ATOM argument is located on a failed image and to add the optional argument
25 STAT.

26 The STAT argument shall be a noncoindexed scalar of type integer. It is an INTENT(OUT) argument.

27 8.5.2 IMAGE_INDEX

28 The intrinsic function IMAGE_INDEX in ISO/IEC 1539-1:2010 is modified by adding two additional versions
29 that specify the team with the argument TEAM or the argument TEAM_ID, and a modified result if either of
30 these versions is invoked.

31 The TEAM argument shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_-
32 ENV. Its value shall represent the current or an ancestor team.

33 The TEAM_ID argument shall be a positive integer scalar. If the current team is the initial team, its value is
34 ignored. Otherwise, its value shall be that of a team identifier for a team that was formed by execution of a
35 FORM TEAM statement for the current team.

36 8.5.3 MOVE_ALLOC

37 The intrinsic subroutine MOVE_ALLOC in ISO/IEC 1539-1:2010, as modified by ISO/IEC 1539-1:2010/Cor
38 2:2013, is modified to take account of the possibility of failed images and to add two optional arguments, STAT
39 and ERRMSG, and a modified result if either is present.

40 The STAT argument shall be a noncoindexed integer scalar with a decimal exponent range of at least four. It is
41 an INTENT(OUT) argument.

1 The ERRMSG argument shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

2 If the execution is successful

- 3 (1) The allocation status of TO becomes unallocated if FROM is unallocated on entry to MOVE_-
4 ALLOC. Otherwise, TO becomes allocated with dynamic type, type parameters, array bounds,
5 array cobounds, and value identical to those that FROM had on entry to MOVE_ALLOC.
- 6 (2) If TO has the TARGET attribute, any pointer associated with FROM on entry to MOVE_ALLOC
7 becomes correspondingly associated with TO. If TO does not have the TARGET attribute, the
8 pointer association status of any pointer associated with FROM on entry becomes undefined.
- 9 (3) The allocation status of FROM becomes unallocated.

10 When a reference to MOVE_ALLOC is executed for which the FROM argument is a coarray, there is an implicit
11 synchronization of all active images of the current team. On each active image, execution of the segment (8.5.2
12 of ISO/IEC 1539-1:2010) following the CALL statement is delayed until all other active images of the current
13 team have executed the same statement the same number of times since execution last began in this team.

14 If the STAT argument appears and execution is successful on all images, the argument is assigned the value
15 zero; if a failed image is detected and execution is otherwise successful, the STAT= specifier is assigned the value
16 STAT_FAILED_IMAGE in the intrinsic module ISO_FORTRAN_ENV.

17 If the STAT argument appears and an error condition occurs, the argument is assigned the value STAT_-
18 STOPPED_IMAGE in the intrinsic module ISO_FORTRAN_ENV if the reason is that a successful execution would
19 have involved an interaction with an image that has initiated termination; otherwise, the value is a processor-
20 dependent positive value that is different from the value of STAT_STOPPED_IMAGE or STAT_FAILED_IMAGE.

21 If the STAT argument does not appear and an error condition occurs or an image involved in execution of the
22 statement has failed, error termination is initiated.

23 If the ERRMSG argument is present and an error condition occurs, the processor shall assign an explanatory
24 message to the argument. If no error condition occurs, the processor shall not change the value of the argument.

25 **8.5.4 NUM_IMAGES**

26 The intrinsic function NUM_IMAGES in ISO/IEC 1539-1:2010 is modified by adding two versions that specify
27 the team with the argument TEAM or the argument TEAM_ID, and a modified result if either of these versions
28 is invoked.

29 The TEAM argument shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_-
30 ENV. Its value shall represent the current or an ancestor team.

31 The TEAM_ID argument shall be a positive integer scalar. If the current team is the initial team, its value is
32 ignored. Otherwise, its value shall be that of a team identifier for a team that was formed by execution of a
33 FORM TEAM statement for the current team.

34 **8.5.5 THIS_IMAGE**

35 The intrinsic function THIS_IMAGE in ISO/IEC 1539-1:2010, as modified by ISO/IEC 1539-1:2010/Cor 1:2012,
36 is modified by adding an optional argument TEAM and a modified result if TEAM is present.

37 The TEAM argument shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_-
38 ENV. Its value shall represent the current or an ancestor team. If TEAM is present, the result is the image index
39 that the invoking image has in the team specified by the value of TEAM; otherwise, the result value is the image
40 index of the invoking image in the current team.

9 Required editorial changes to ISO/IEC 1539-1:2010(E)

9.1 General

The following editorial changes, if implemented, would provide the facilities described in foregoing clauses of this Technical Specification. Descriptions of how and where to place the new material are enclosed in braces {}. Edits to different places within the same clause are separated by horizontal lines.

In the edits, except as specified otherwise by the editorial instructions, underwave (underwave) and strike-out (~~strike-out~~) are used to indicate insertion and deletion of text.

9.2 Edits to Introduction

{In paragraph 1 of the Introduction}

After “informally known as Fortran 2008, plus the facilities defined in ISO/IEC TS 29113:2012” add “and ISO/IEC TS 18508:2015”.

{In the Introduction and after the paragraph added by ISO/IEC TS 29113:2012, insert new paragraph}

• Features previously described in ISO/IEC TS 18508:2015:

Optional STAT= and ERRMSG= specifiers are added to the CRITICAL statement. Optional arguments are added to the intrinsic procedures ATOMIC_DEFINE, ATOMIC_REF, IMAGE_INDEX, MOVE_ALLOC, NUM_IMAGES, and THIS_IMAGE. Extensions of image selector syntax permit designation of coarrays across team boundaries and optional STAT= specifiers. The STOPPED_IMAGES intrinsic procedure provides the indices of stopped images. The teams facility uses the CHANGE TEAM construct, TEAM_TYPE derived type, FORM TEAM and SYNC TEAM statements, and the GET_TEAM and TEAM_ID intrinsic procedures, to provide a capability for a subset of the images of the program to act as if it consists of all images for the purposes of image index values, coarray allocations, and synchronization. The collective subroutines CO_BROADCAST, CO_MAX, CO_MIN, CO_REDUCE, and CO_SUM perform computations based on values on all active images of the current team, offering the possibility of efficient execution of reduction operations. The additional atomic subroutines ATOMIC_ADD, ATOMIC_AND, ATOMIC_CAS, ATOMIC_FETCH_ADD, ATOMIC_FETCH_AND, ATOMIC_FETCH_OR, ATOMIC_FETCH_XOR, ATOMIC_OR, and ATOMIC_XOR perform integer addition, compare and swap, and bitwise computations. The event facility uses the EVENT POST and EVENT WAIT statements, the EVENT_TYPE derived type, and the EVENT_QUERY intrinsic procedure to allow one-sided ordering of execution segments. The FAIL TEAM statement, the FAILED_IMAGES and IMAGE_STATUS intrinsic procedures, and the defined constant STAT_FAILED_IMAGE provide support for continued execution after one or more images have failed.

9.3 Edits to clause 1

{In 1.3 Terms and definitions, insert new terms as follows}

1.3.8a

asynchronous progress

ability of images to define or reference coarrays without requiring the images on which the data reside to execute any particular statements

1.3.30a

collective subroutine

1 intrinsic subroutine that is invoked on the active images of the current team to perform a calculation on those
2 images and assign the computed value on one or all of them (13.1)

3 **1.3.68a**

4 **established coarray**

5 coarray that is accessible within a CHANGE TEAM construct from outside the construct (8.1.4a)

6 **1.3.83a**

7 **active image**

8 an image that has not failed or initiated termination (2.3.6)

9 **1.3.83b**

10 **failed image**

11 an image for which references or definitions of a variable on the image fail when that variable should be accessible;
12 or an image that is not a stopped image and fails to respond during the execution of an image control statement
13 or a reference to a collective subroutine (2.3.6)

14 **1.3.83d**

15 **stopped image**

16 an image that has initiated normal termination (2.3.6)

17 **1.3.145a**

18 **team**

19 set of images that can readily execute independently of other images (2.3.4)

20 **1.3.145a.1**

21 **current team**

22 the team specified in the CHANGE TEAM statement of the innermost executing CHANGE TEAM construct,
23 or the initial team if no CHANGE TEAM construct is active (2.3.4)

24 **1.3.145a.2**

25 **initial team**

26 the current team when the program began execution (2.3.4)

27 **1.3.145a.3**

28 **parent team**

29 team from which the current team was formed by executing a FORM TEAM statement (2.3.4)

30 **1.3.145a.4**

31 **team identifier**

32 integer value identifying a team (2.3.4)

33 **1.3.154.1-**

34 **event variable**

35 scalar variable of type EVENT_TYPE (13.8.2.8a) from the intrinsic module ISO_FORTRAN_ENV

36 **1.3.154.3**

37 **team variable**

38 scalar variable of type TEAM_TYPE (13.8.2.26) from the intrinsic module ISO_FORTRAN_ENV

39 **9.4 Edits to clause 2**

40 {In 2.1 High level syntax, Add new construct and statements into the syntax list as follows: In R213 *executable-*
41 *construct* insert alphabetically “*change-team-construct*”; in R214 *action-stmt* insert alphabetically “*event-post-*
42 *stmt*”, “*event-wait-stmt*”, “*fail-image-stmt*”, “*form-team-stmt*”, and “*sync-team-stmt*”.

43 {In 2.3.4 Program execution, after the first paragraph, insert 5.1, paragraphs 1 and 2, of this Technical Spe-

1 cification with the following changes: In the first paragraph delete “in ISO/IEC 1539-1:2010” following “R624”
 2 and insert “(8.5.2c)” following “FORM TEAM statement”. In the second paragraph insert “(8.1.4a)” following
 3 “CHANGE TEAM construct”. }

4 {After 2.3.5 Execution sequence, insert a new subclause “2.3.6 Image execution states” consisting of five para-
 5 graphs, with the third, fourth, and fifth paragraphs consisting of the first three paragraphs of 6.1 Introduction
 6 and Note 6.1 of this Technical Specification after changing “(6.4)” in the second paragraph to “13.8.2.21b”, and
 7 the first and second paragraphs as follows.}

8 A stopped image is an image that has initiated termination of execution.

9 An active image is an image that is not a failed image or a stopped image.

10 {In 2.4.7 Coarray, after the first paragraph, insert 5.1 paragraph 3 of this Technical Specification.}

11 {In 2.4.7 Coarray, edit the second paragraph as follows.}

12 For each coarray on an image in a team, there is a corresponding coarray with the same type, type parameters,
 13 and bounds on every other image in that team.

14 {In 2.4.7 Coarray, edit the first sentence of the third paragraph as follows.}

15 The set of corresponding coarrays on all images in a team is arranged in a rectangular pattern.

16 9.5 Edits to clause 4

17 {In 4.5.2.1 Syntax, edit constraint C433 as follows}

18 C433 (R425) If EXTENDS appears and the type being defined has ~~an ultimate~~ a component of type EVENT_TYPE
 19 or LOCK_TYPE from the intrinsic module ISO_FORTRAN_ENV, at any level of nonpointer component selection,
 20 its parent type shall have ~~an ultimate~~ a component at some level of nonpointer component selection of type
 21 EVENT_TYPE or LOCK_TYPE, respectively.

22 {In 4.5.6.2 The finalization process, add to the end of NOTE 4.48}

23 in the current team

24 9.6 Edits to clause 6

25 {In 6.6 Image selectors, replace R624 with}

26 R624 *image-selector* is *lbracket cosubscript-list* ■
 27 ■ [, *team-identifier*] [, STAT = *stat-variable*] *rbracket*

28 R624a *team-identifier* is TEAM_ID = *scalar-int-expr*
 29 or TEAM = *team-variable*

30 C627a (R624) *stat-variable* shall not be a coindexed object.

31 {In 6.6 Image selectors, edit the last sentence of the second paragraph as follows.}

32 An image selector shall specify an image index value that is not greater than the number of images in the team
 33 specified by a *team-identifier* if it appears, or in the current team otherwise.

34 {In 6.6 Image selectors, after paragraph 2 insert the two paragraphs following C509 in 5.4 of this Technical
 35 Specification with the following change: following “FORM TEAM statement” insert “(8.5.2c)” }

1 {In 6.7.1.2, Execution of an ALLOCATE statement, edit paragraphs 3 and 4 as follows}

2 If an *allocation* specifies a coarray, its dynamic type and the values of corresponding type parameters shall be
 3 the same on every active image in the current team. The values of corresponding bounds and corresponding
 4 cobounds shall be the same on every image these images. If the coarray is a dummy argument, its ultimate
 5 argument (12.5.2.3) shall be the same coarray on every image these images.

6 When an ALLOCATE statement is executed for which an *allocate-object* is a coarray, there is an implicit syn-
 7 chronization of all active images in the current team. On ~~each image these images~~, execution of the segment
 8 (8.5.2) following the statement is delayed until all other active images in the current team have executed the
 9 same statement the same number of times since execution last began in this team.

10 {In 6.7.3.2, Deallocation of allocatable variables, edit paragraphs 11 and 12 as follows}

11 When a DEALLOCATE statement is executed for which an *allocate-object* is a coarray, there is an implicit
 12 synchronization of all active images in the current team. On ~~each image these images~~, execution of the segment
 13 (8.5.2) following the statement is delayed until all other active images in the current team have executed the
 14 same statement the same number of times since execution last began in this team. If the coarray is a dummy
 15 argument, its ultimate argument (12.5.2.3) shall be the same coarray on every image these images.

16 There is also an implicit synchronization of all active images in the current team in association with the deallo-
 17 cation of a coarray or coarray subcomponent caused by the execution of a RETURN or END statement or the
 18 termination of a BLOCK construct.

19 {In 6.7.4 STAT=specifier, edit paragraph 2 as follows}

20 If the STAT= specifier appears, successful execution of the ALLOCATE or DEALLOCATE statement on all
 21 images in the current team causes the *stat-variable* to become defined with the value zero; otherwise, if a failed
 22 image is detected and execution is otherwise successful, the STAT= specifier is assigned the value of the named
 23 constant STAT_FAILED_IMAGE in the intrinsic module ISO_FORTRAN_ENV (13.8.2).

24 {In 6.7.4 STAT= specifier, para 3, replace the text to the bullet list with}

25 If the STAT= specifier appears in an ALLOCATE or DEALLOCATE statement with a coarray *allocate-object*
 26 and an error condition occurs, the specified variable is assigned a positive value. The value shall be that of the
 27 named constant STAT_STOPPED_IMAGE in the intrinsic module ISO_FORTRAN_ENV if the reason is that a
 28 successful execution would have involved an interaction with an image that has initiated termination; otherwise,
 29 the value is a processor-dependent positive value that is different from the values of the named constants STAT_-
 30 STOPPED_IMAGE or STAT_FAILED_IMAGE in the intrinsic module ISO_FORTRAN_ENV. In all of these
 31 cases, each *allocate-object* has a processor-dependent allocation status:

32 {At the end of 6.7.4 STAT= specifier, append the following new paragraph}

33 If the STAT argument does not appear and an error condition occurs or an image involved in execution of the
 34 statement has failed, error termination is initiated.

35 9.7 Edits to clause 8

36 {In 8.1.1 General, paragraph 1, following the BLOCK construct entry in the list of constructs insert}

- 37 • CHANGE TEAM construct;
-

38 {Following 8.1.4 BLOCK construct insert 5.3 CHANGE TEAM construct from this Technical Specification as
 39 8.1.4a, with rule, constraint, and Note numbers modified, the reference “(5.2)” in C506 changed to “(13.8.2.26)”,
 40 and in the third paragraph following C508, delete “of ISO/IEC 1539-1:2010”. }

1 {In 8.1.5 CRITICAL construct: In para 1, line 1, after “one image” add “in the current team”. In para 1, at the
 2 end of R811, add “[*sync-stat-list*]”. In para 2, line 1, at the end of the sentence, add “or the executing image
 3 fails”. After para 2 add the paragraph following R811 in 6.3 CRITICAL construct of this Technical Specification.
 4 In para 3, line 1, after “other image” add “in the current team”.}

5 {Following 8.4 STOP and ERROR STOP statements, insert 6.2 FAIL IMAGE statement from this Technical
 6 Specification as 8.4a, with rule and Note numbers modified.}

7 {In 8.5.1 Image control statements, paragraph 2, insert extra bullet points following the CRITICAL and END
 8 CRITICAL line}

- 9 • CHANGE TEAM and END TEAM;
 - 10 • EVENT POST and EVENT WAIT;
 - 11 • FORM TEAM;
 - 12 • SYNC TEAM;
-

13 {In 8.5.1 Image control statements, edit paragraph 3 as follows}

14 All image control statements except CRITICAL, END CRITICAL, EVENT POST, EVENT WAIT, FORM
 15 TEAM, LOCK, and UNLOCK include the effect of executing a SYNC MEMORY statement (8.5.5).

16 {In 8.5.2 Segments, after the first sentence of paragraph 3, insert the following }

17 A coarray that is of type EVENT_TYPE (13.8.2.8a) may be referenced or defined during the execution of a
 18 segment that is unordered relative to the execution of another segment in which that coarray of type EVENT_
 19 TYPE is defined.

20 {In 8.5.2 Segments, edit the first sentence of NOTE 8.34 as follows}

21 The model upon which the interpretation of a program is based is that there is a permanent memory location for
 22 each coarray and that all images on which it is established can access it.

23 {Following 8.5.2 Segments insert 7.3 EVENT POST statement from this Technical Specification as 8.5.2a, with
 24 rule and constraint numbers modified, and change the “(7.2)” in C704 to “(13.8.2.8a)”. }

25 {Following 8.5.2 Segments insert 7.4 EVENT WAIT statement from this Technical Specification as 8.5.2b, with
 26 rule and constraint numbers modified.}

27 {Following 8.5.2 Segments insert 5.5 FORM TEAM statement from this Technical Specification as 8.5.2c, with
 28 rule and Note numbers modified.}

29 {In 8.5.3 SYNC ALL statement, edit paragraph 2 as follows}

30 Execution of a SYNC ALL statement performs a synchronization of all active images in the current team.
 31 Execution on an image, M, of the segment following the SYNC ALL statement is delayed until each other active
 32 image in the current team has executed a SYNC ALL statement as many times as has image M since execution
 33 last began in this team. The segments that executed before the SYNC ALL statement on an image precede the
 34 segments that execute after the SYNC ALL statement on another image.

35 {In 8.5.4 SYNC IMAGES, edit paragraphs 1 through 4 as follows}

36 If *image-set* is an array expression, the value of each element shall be positive and not greater than the number
 37 of images in the current team, and there shall be no repeated values.

38 If *image-set* is a scalar expression, its value shall be positive and not greater than the number of images in the

1 current team.

2 An *image-set* that is an asterisk specifies all images in the current team.

3 Execution of a SYNC IMAGES statement performs a synchronization of the image with each of the other active
4 images in the *image-set*. Executions of SYNC IMAGES statements on images M and T correspond if the number
5 of times image M has executed a SYNC IMAGES statement in the current team with T in its image set since
6 execution last began in this team is the same as the number of times image T has executed a SYNC IMAGES
7 statement in the current team with M in its image set since execution last began in this team. The segments
8 that executed before the SYNC IMAGES statement on either image precede the segments that execute after the
9 corresponding SYNC IMAGES statement on the other image.

10 {Following 8.5.5 SYNC MEMORY statement, insert 5.6 SYNC TEAM statement from this Technical Specification
11 as 8.5.5a, with the rule number modified.}

12 {In 8.5.6 LOCK and UNLOCK statements: in para 1, change “image and” to “image, that image has not failed,
13 and the lock variable”; in para 4, add new second sentence “If an image fails after locking and before unlocking
14 a lock variable, the variable becomes unlocked.”}

15 {In 8.5.7 STAT= and ERRMSG= specifiers in image control statements replace paragraphs 1 and 2 by}

16 If the STAT= specifier appears in a CHANGE TEAM, END TEAM, EVENT POST, EVENT WAIT, FORM
17 TEAM, LOCK, SYNC ALL, SYNC IMAGES, SYNC MEMORY, SYNC TEAM, or UNLOCK statement and its
18 execution is successful on the involved images, the specified variable is assigned the value zero; otherwise, if a
19 failed image is detected and execution is otherwise successful, the STAT= specifier is assigned the value of the
20 named constant STAT_FAILED_IMAGE in the intrinsic module ISO_FORTRAN_ENV (13.8.2).

21 If the STAT= specifier appears in a CHANGE TEAM, END TEAM, EVENT POST, EVENT WAIT, FORM
22 TEAM, LOCK, SYNC ALL, SYNC IMAGES, SYNC MEMORY, SYNC TEAM, or UNLOCK statement and
23 an error condition occurs, the specified variable is assigned a positive value. The value shall be the named
24 constant STAT_STOPPED_IMAGE in the intrinsic module ISO_FORTRAN_ENV if the reason is that a successful
25 execution would have involved an interaction with an image that has initiated termination; otherwise, the value is
26 a processor-dependent positive value that is different from the values of the named constants STAT_STOPPED_
27 IMAGE or STAT_FAILED_IMAGE in the intrinsic module ISO_FORTRAN_ENV.

28 The set of images involved in execution of an END TEAM, FORM TEAM, or SYNC ALL statement is that of
29 the current team. The set of images involved in execution of a CHANGE TEAM or SYNC TEAM statement is
30 that of the team specified by the value of the specified *team-variable*. The set of images involved in execution
31 of a SYNC IMAGES statement is the union of its *image-set* and the executing image. The images involved in
32 execution of a LOCK or UNLOCK statement are the ones on which the referenced lock variable is located and
33 the executing image. The images involved in execution of an EVENT POST statement are the ones on which
34 the referenced event variable is located and the executing image.

35 After execution of an image control statement with a STAT= specifier, all failed images involved in the statement
36 shall be known by the executing image to have failed.

37 If the STAT= specifier appears in a CHANGE TEAM, END TEAM, SYNC ALL, SYNC IMAGES, or SYNC
38 TEAM statement and an error condition occurs, the effect is the same as that of executing the SYNC MEMORY
39 statement, except for defining the STAT= variable.

40 {In 8.5.7 STAT= and ERRMSG= specifiers in image control statements replace paragraphs 4 and 5 by}

41 If the STAT= specifier does not appear in a CHANGE TEAM, END TEAM, EVENT POST, EVENT WAIT,
42 FORM TEAM, LOCK, SYNC ALL, SYNC IMAGES, SYNC MEMORY, SYNC TEAM, or UNLOCK statement
43 and its execution is not successful or an image involved in execution of the statement has failed, error termination
44 is initiated.

45 If an ERRMSG= specifier appears in a CHANGE TEAM, END TEAM, EVENT POST, EVENT WAIT, FORM

1 TEAM, LOCK, SYNC ALL, SYNC IMAGES, SYNC MEMORY, SYNC TEAM, or UNLOCK statement and
 2 its execution is not successful, the processor shall assign an explanatory message to the specified variable. If the
 3 execution is successful, the processor shall not change the value of the variable.

4 9.8 Edits to clause 9

5 {In 9.5.1, Referring to a file, edit the first sentence of paragraph 4 as follows}

6 In a READ statement, an *io-unit* that is an asterisk identifies an external unit that is preconnected for sequential
 7 formatted input on image 1 in the initial team only (9.6.4.3).

8 9.9 Edits to clause 13

9 {In 13.1 Classes of intrinsic procedures, edit paragraph 1 as follows}

10 Intrinsic procedures are divided into seven eight classes: inquiry functions, elemental functions, transformational
 11 functions, elemental subroutines, pure subroutines, atomic subroutines, collective subroutines, and (impure)
 12 subroutines.

13 {In 13.1 Classes of intrinsic procedures, replace paragraph 3 by paragraphs 1 through 4 and NOTES 8.1 and 8.2
 14 of 8.2 Atomic subroutines of this Technical Specification, with these changes: Delete “of ISO/IEC 1539-1:2010”
 15 and renumber the NOTES.}

16 {In 13.1 Classes of intrinsic procedures, insert the contents of 8.3 Collective subroutines of this Technical Specifica-
 17 tion after paragraph 3 and Note 13.1, with these changes: In paragraph 2 of 8.3, delete “of ISO/IEC 1539-1:2010”;
 18 In paragraph 5 of 8.3, add “(13.8.2)” after the first “ISO_FORTRAN_ENV”.}

19 {In 13.5 Standard generic intrinsic procedures, paragraph 2 after the line “A indicates ... atomic subroutine”
 20 insert a new line}

21 C indicates that the procedure is a collective subroutine

22 {In 13.5 Standard generic intrinsic procedures, Table 13.1, insert new entries into the table, alphabetically}

ATOMIC_ADD	(ATOM, VALUE [, STAT])	A	Atomic add operation.
ATOMIC_AND	(ATOM, VALUE [, STAT])	A	Atomic bitwise AND operation.
ATOMIC_CAS	(ATOM, OLD, COMPARE, NEW [, STAT])	A	Atomic compare and swap.
ATOMIC_FETCH_ADD	(ATOM, VALUE, OLD [,STAT])	A	Atomic fetch and add operation.
ATOMIC_FETCH_AND	(ATOM, VALUE, OLD [,STAT])	A	Atomic fetch and bitwise AND operation.
ATOMIC_FETCH_OR	(ATOM, VALUE, OLD [,STAT])	A	Atomic fetch and bitwise OR operation.
ATOMIC_FETCH_XOR	(ATOM, VALUE, OLD [,STAT])	A	Atomic fetch and bitwise exclusive OR operation.
ATOMIC_OR	(ATOM, VALUE [, STAT])	A	Atomic bitwise OR operation.
ATOMIC_XOR	(ATOM, VALUE [, STAT])	A	Atomic bitwise exclusive OR operation.
CO_BROADCAST	(A, SOURCE_IMAGE [, STAT, ERRMSG])	C	Copy a value to all images of the current team.
CO_MAX	(A [, RESULT_IMAGE, STAT, ERRMSG])	C	Compute maximum of elements across images.
CO_MIN	(A [, RESULT_IMAGE, STAT, ERRMSG])	C	Compute minimum of elements across images.
CO_REDUCE	(A, OPERATOR	C	General reduction of elements across images.

	[, RESULT_IMAGE, STAT, ERRMSG])		
CO_SUM	(A [, RESULT_IMAGE, STAT, ERRMSG])	C	Sum elements across images.
EVENT_QUERY	(EVENT, COUNT [, STAT])	A	Count of an event variable.
FAILED_IMAGES	([TEAM, KIND])	T	Indices of failed images.
GET_TEAM	([LEVEL])	T	Team value.
IMAGE_STATUS	(IMAGE [, TEAM])	E	Status of images.
STOPPED_IMAGES	([TEAM, KIND])	T	Indices of stopped images.
TEAM_ID	([TEAM])	T	Team identifier.

1 {In 13.5 Standard generic intrinsic procedures, Table 13.1, edit the entries for ATOMIC_DEFINE, ATOMIC_REF,
2 IMAGE_INDEX, MOVE_ALLOC, NUM_IMAGES, and THIS_IMAGE, as modified by ISO/IEC 1539-1:2010/Cor
3 1:2012, as follows}

ATOMIC_DEFINE	(ATOM, VALUE [, <u>STAT</u>])	A	Define a variable atomically.
ATOMIC_REF	(VALUE, ATOM [, <u>STAT</u>])	A	Reference a variable atomically.
IMAGE_INDEX	(COARRAY, SUB) or (<u>COARRAY, SUB, TEAM</u>) or (<u>COARRAY, SUB, TEAM_ID</u>)	I	Image index from cosubscripts.
MOVE_ALLOC	(FROM, TO [, <u>STAT, ERRMSG</u>])	PS	Move an allocation.
NUM_IMAGES	() or (<u>TEAM</u>) or (<u>TEAM_ID</u>)	T	Number of images.
THIS_IMAGE	([<u>TEAM</u>])	T	Index of the invoking image.
THIS_IMAGE	(COARRAY [, <u>TEAM</u>] or (COARRAY, DIM [, <u>TEAM</u>])	T	Cosubscript(s) for this image.

4 {In 13.5, Standard generic intrinsic procedures, paragraph 3, insert “in the initial team” after “image 1” }

5 {In 13.7 Specifications of the standard intrinsic procedures, insert subclauses 8.4.1 through 8.4.20 of this Technical
6 Specification in order alphabetically, with subclause numbers adjusted accordingly.}

7 {In 13.7.20 ATOMIC_DEFINE, edit the subclause title as follows}

8 13.7.20 ATOMIC_DEFINE (ATOM, VALUE [, STAT])

9 {In 13.7.20 ATOMIC_DEFINE, add the argument description as follows}

10 STAT (optional) shall be a noncoindexed integer scalar with a decimal range of at least four. It is an IN-
11 TENT(OUT) argument.

12 {In 13.7.21 ATOMIC_REF, edit the subclause title as follows}

13 13.7.21 ATOMIC_REF (VALUE, ATOM [, STAT])

14 {In 13.7.21 ATOMIC_REF, add the argument description and a paragraph as follows}

1 STAT (optional) shall be a noncoindexed integer scalar with a decimal range of at least four. It is an IN-
2 TENT(OUT) argument.

3 If an error condition occurs, the VALUE argument becomes undefined.

4 {In 13.7.79 IMAGE_INDEX, edit the subclause title as follows}

5 13.7.79 IMAGE_INDEX (COARRAY, SUB) or IMAGE_INDEX (COARRAY, SUB, TEAM) or IMAGE_INDEX
6 (COARRAY, SUB, TEAM_ID)

7 {In 13.7.79 IMAGE_INDEX, edit the COARRAY argument description as follows}

8 COARRAY shall be a coarray of any type. If the function is invoked with a TEAM_ID argument, it shall be
9 established in an ancestor of the specified team. Otherwise, it shall be established in the specified
10 team.

11 {In 13.7.79 IMAGE_INDEX, add the arguments descriptions as follows}

12 TEAM shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_ENV. Its
13 value shall represent the current or an ancestor team.

14 TEAM_ID shall be a positive integer scalar. If the current team is the initial team, its value is ignored.
15 Otherwise, its value shall be that of a team identifier for a team that was formed by execution of a
16 FORM TEAM statement for the current team.

17 If TEAM appears, it specifies the team. Otherwise, the team specified is the current team.

18 {In 13.7.79 IMAGE_INDEX, replace paragraph 5 with}

19 **Result Value.** If the value of SUB is a valid sequence of cosubscripts for COARRAY in the specified team, the
20 result is the index of the corresponding image in that team. Otherwise, the result is zero.

21 {In 13.7.118 MOVE_ALLOC, edit the subclause title as follows}

22 13.7.118 MOVE_ALLOC (FROM, TO [, STAT, ERRMSG])

23 {In 13.7.118 MOVE_ALLOC, add the arguments descriptions as follows}

24 STAT (optional) shall be a noncoindexed default integer scalar. It is an INTENT(OUT) argument.

25 ERRMSG (optional) shall be a noncoindexed default character scalar. It is an INTENT(INOUT) argument.

26 {In 13.7.118 MOVE_ALLOC, replace paragraphs 4 through 6 and the paragraph that was added by ISO/IEC
27 1539-1:2010/Cor 2:2013 by paragraphs 4 through 8 of 8.5.3 of this Technical Specification, deleting “of ISO/IEC
28 1539-1:2010” in paragraph 5.}

29 {In 13.7.126 NUM_IMAGES, edit the subclause title as follows}

30 13.7.126 NUM_IMAGES () or NUM_IMAGES (TEAM) or NUM_IMAGES (TEAM_ID)

31 {In 13.7.126 NUM_IMAGES, replace paragraph 3 with}

32 **Arguments.**

33 TEAM shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_ENV. Its
34 value shall represent the current or an ancestor team.

35 TEAM_ID shall be a positive integer scalar. If the current team is the initial team, its value is ignored.
36 Otherwise, its value shall be that of a team identifier for a team that was formed by execution of a
37 FORM TEAM statement for the current team.

1 If TEAM appears, it specifies the team. Otherwise, the team specified is the current team.

2 {In 13.7.126 NUM_IMAGES, replace paragraph 5 with}

3 **Result Value.** The number of images in the team specified.

4 {In 13.7.165, as modified by ISO/IEC 1539-1:2010/Cor 1:2012, THIS_IMAGE () or THIS_IMAGE (COARRAY)
5 or THIS_IMAGE (COARRAY, DIM) edit the subclause title as follows }

6 13.7.165 THIS_IMAGE ([TEAM]) or THIS_IMAGE (COARRAY [, TEAM]) or THIS_IMAGE (COARRAY, DIM
7 [, TEAM])

8 {In 13.7.165, as modified by ISO/IEC 1539-1:2010/Cor 1:2012, THIS_IMAGE () or THIS_IMAGE (COARRAY)
9 or THIS_IMAGE (COARRAY, DIM) insert a new argument at the end of paragraph 3 }

10 TEAM (optional) shall be a scalar of type TEAM_TYPE defined in the intrinsic module ISO_FORTRAN_
11 ENV. Its value shall represent the current or an ancestor team. If COARRAY appears, it shall be
12 established for TEAM.

13 {In 13.7.165, as modified by ISO/IEC 1539-1:2010/Cor 1:2012, THIS_IMAGE () or THIS_IMAGE (COARRAY)
14 or THIS_IMAGE (COARRAY, DIM) at the end of paragraph 5 add }

15 *Case (iv):* The result of THIS_IMAGE (TEAM) is a scalar with a value equal to the index of the invoking
16 image in the team specified by the value of TEAM.

17 *Case (v):* The result of THIS_IMAGE (COARRAY, TEAM) is the sequence of cosubscript values for
18 COARRAY that would specify the invoking image in the team specified by the value of TEAM.

19 *Case (vi):* The result of THIS_IMAGE (COARRAY, DIM, TEAM) is the value of cosubscript DIM in the
20 sequence of cosubscript values for COARRAY that would specify the invoking image in the team
21 specified by the value of TEAM.

22 {In 13.7.172 UCBOUND, edit the Result Value as follows.}

23 The final upper cobound is the final cosubscript in the cosubscript list for the coarray that selects the image with
24 index NUM_IMAGES(→) equal to the number of images in the current team when the coarray was established.

25 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, insert a new subclause}

26 13.8.2.7a CURRENT_TEAM

27 The value of the default integer scalar constant CURRENT_TEAM identifies the current team in an invocation
28 of the function GET_TEAM.

29 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, insert a new subclause 13.8.2.8a consisting of subclause
30 7.2 EVENT_TYPE of this Technical Specification, but omitting the final sentence of the first paragraph and the
31 fourth sentence of the second paragraph.}

32 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, insert a new subclause}

33 13.8.2.9a INITIAL_TEAM

34 The value of the default integer scalar constant INITIAL_TEAM identifies the initial team in an invocation of
35 the function GET_TEAM.

36 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, insert a new subclause}

37 13.8.2.19a PARENT_TEAM

38 The value of the default integer scalar constant PARENT_TEAM identifies the parent team in an invocation of

1 the function GET_TEAM.

2 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, insert a new subclause 13.8.2.21b consisting of subclause
3 6.4 STAT_FAILED_IMAGE of this Technical Specification.}

4 {In 13.8.2.24 STAT_STOPPED_IMAGE, edit the paragraph as follows.}

5 The value of the default integer scalar constant STAT_STOPPED_IMAGE is assigned to the variable specified
6 in a STAT= specifier (6.7.4, 8.5.7) or a STAT argument in a call to a collective subroutine if execution of the
7 statement with that specifier or argument requires synchronization with an image that has initiated termination
8 of execution. This value shall be positive ~~and different from the value of IOSTAT_INQUIRE_INTERNAL_UNIT.~~

9 {In 13.8.2.24 STAT_STOPPED_IMAGE, insert a new Note after paragraph 1}

10 In addition to detecting that an image has initiated normal termination by having the variable in a STAT=specifier
11 or a STAT argument of a call to a collective subroutine assigned the value STAT_STOPPED_IMAGE, an image
12 can get the indices of the images that have initiated normal termination in a specified team by invoking the
13 intrinsic function STOPPED_IMAGES.

14 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, append a new subclause 13.8.2.26 consisting of subclause
15 5.2 TEAM_TYPE of this Technical Specification, but omitting the final sentence of the first paragraph.}

16 {In 13.8.2 The ISO_FORTRAN_ENV intrinsic module, append a new subclause}

17 13.8.2.26a Uniqueness of values of named constants

18 The values of the named constants IOSTAT_INQUIRE_INTERNAL_UNIT, STAT_FAILED_IMAGE, STAT_
19 LOCKED, STAT_LOCKED_OTHER_IMAGE STAT_STOPPED_IMAGE, and STAT_UNLOCKED shall be dis-
20 tinct.

21 9.10 Edits to clause 16

22 {In 16.4 Statement and construct entities, in paragraph 1, after “DO CONCURRENT” replace “or” with a
23 comma; after “ASSOCIATE construct” insert “, or as a coarray specified by a *codimension-decl* in a CHANGE
24 TEAM construct.”}

25 {In 16.4 Statement and construct entities, add the following new paragraph after paragraph 8}

26 The associate names of a CHANGE TEAM construct have the scope of the block. They have the declared type,
27 dynamic type, type parameters, rank, bounds, and cobounds as specified in 8.1.4a.

28 {In 16.5.1.6 Construct association, append the following sentence to the paragraph 1}

29 Execution of a CHANGE TEAM statement establishes an association between each coselector and the corres-
30 ponding associate name of the construct.

31 {In 16.6.5 Events that cause variables to become defined, add the following list item}

32 (33) Failure of the image that locked a lock variable before it has unlocked the variable causes the variable to
33 become unlocked.

34 {In 16.6.6 Events that cause variables to become undefined, add the following list item}

35 (27) When an image fails during the execution of a segment, a data object on a non-failed image becomes
36 undefined if it might be defined or undefined by execution of a statement of the segment other than an invocation
37 of an atomic subroutine.

1 {In 16.6.7, Variable definition context, after item (13) insert a new list item}

2 (13a) a coarray in a *codimension-decl* in a CHANGE TEAM construct if the coarray named by the corresponding
3 *coselector-name* of that construct appears in a variable definition context within that construct;

4 {In 16.6.7, at the end of the list of variable definition contexts in para 1, replace the “.” at the end of entry (15)
5 with “;” and add two new entries as follows}

6 (16) a *team-variable* in a FORM TEAM statement;

7 (17) an *event-variable* in an EVENT POST or EVENT WAIT statement.

8 **9.11 Edits to annex A**

9 {In A.2 Processor dependencies, in the list item beginning “the effect of calling COMMAND_ARGUMENT_
10 COUNT”, insert “in the initial team” after “image 1”.}

11 {In A.2 Processor dependencies, in the list item beginning “the value assigned to a CMDSTAT”, replace “CM-
12 DSTAT or STATUS” with “CMDSTAT, STAT, or STATUS” .}

13 {At the end of A.2 Processor dependencies, replace the final full stop with a semicolon and add new items as
14 follows}

- 15 • the conditions that cause an image to fail (13.8.2.21b);
- 16 • the computed value of the CO_SUM intrinsic subroutine (13.7.42e);
- 17 • the computed value of the CO_REDUCE intrinsic subroutine (13.7.42d);
- 18 • how sequences of event posts in unordered segments interleave with each other (8.5.2a);
- 19 • the image index value assigned by a FORM TEAM statement without a NEW INDEX= specifier (8.5.2c);
- 20 • the value of an expression that includes a reference to a coindexed object on a failed image (2.3.6).

21 **9.12 Edits to annex C**

22 {In C.5 Clause 8 notes, at the end of the subclause insert subclauses A.1.1, A.1.2, A.1.3, A.2.1, A.3.1, A.3.2, and
23 A.3.3 from this Technical Specification as subclauses C.5.5 to C.5.11.}

24 {In C.10 Clause 13 notes, at the end of the subclause insert subclauses A.4.1 and A.4.2 from this Technical
25 Specification as subclauses C.10.2 and C.10.3., deleting “in ISO/IEC 1539-1:2010” in A.4.2.1}

Annex A

(Informative)

Extended notes

A.1 Clause 5 notes

A.1.1 Example using three teams

Compute fluxes over land, sea and ice in different teams based on surface properties. Assumption: Each image deals with areas containing exactly one of the three surface types.

```

8 SUBROUTINE COMPUTE_FLUXES(FLUX_MOM, FLUX_SENS, FLUX_LAT)
9 USE, INTRINSIC :: ISO_FORTRAN_ENV, ONLY: TEAM_TYPE
10 REAL, INTENT(OUT) :: FLUX_MOM(:,,:), FLUX_SENS(:,,:), FLUX_LAT(:,,:)
11 INTEGER, PARAMETER :: LAND=1, SEA=2, ICE=3
12 CHARACTER(LEN=10) :: SURFACE_TYPE
13 INTEGER :: MY_SURFACE_TYPE, N_IMAGE
14 TYPE(Team) :: TEAM_SURFACE_TYPE
15
16 CALL GET_SURFACE_TYPE(THIS_IMAGE(), SURFACE_TYPE) ! Surface type
17 SELECT CASE (SURFACE_TYPE) ! of the executing image
18 CASE ("LAND")
19 MY_SURFACE_TYPE = LAND
20 CASE ("SEA")
21 MY_SURFACE_TYPE = SEA
22 CASE ("ICE")
23 MY_SURFACE_TYPE = ICE
24 CASE DEFAULT
25 ERROR STOP
26 END SELECT
27 FORM TEAM(MY_SURFACE_TYPE, TEAM_SURFACE_TYPE)
28
29 CHANGE TEAM(TEAM_SURFACE_TYPE)
30 SELECT CASE (TEAM_ID( ))
31 CASE (LAND ) ! Compute fluxes over land surface
32 CALL COMPUTE_FLUXES_LAND(FLUX_MOM, FLUX_SENS, FLUX_LAT)
33 CASE (SEA) ! Compute fluxes over sea surface
34 CALL COMPUTE_FLUXES_SEA(FLUX_MOM, FLUX_SENS, FLUX_LAT)
35 CASE (ICE) ! Compute fluxes over ice surface
36 CALL COMPUTE_FLUXES_ICE(FLUX_MOM, FLUX_SENS, FLUX_LAT)
37 CASE DEFAULT
38 ERROR STOP
39 END SELECT
40 END TEAM
41 END SUBROUTINE COMPUTE_FLUXES

```

A.1.2 Accessing coarrays in sibling teams

The following program shows the subdivision of a 4 x 4 grid into 2 x 2 teams and addressing of sibling teams.

```
PROGRAM DEMO
```

```

1  ! Initial team : 16 images. Algorithm design is a 4 x 4 grid.
2  ! Desire 4 teams, for the upper left (UL), upper right (UR),
3  !           Lower left (LL), lower right (LR)
4  USE,INTRINSIC :: ISO_FORTRAN_ENV, ONLY: team_type
5  TYPE (team_type) :: t
6  INTEGER,PARAMETER :: UL=11, UR=22, LL=33, LR=44
7  REAL    :: A(10,10)[4,*]
8  INTEGER :: mype, teamid, newpe
9  INTEGER :: UL_image_list(4) = [1, 2, 5, 6], &
10         LL_image_list(4) = UL_image_list + 2, &
11         UR_image_list(4) = UL_image_list + 8, &
12         LR_image_list(4) = UL_image_list + 10
13
14  mype = THIS_IMAGE()
15  IF (any(mype == UL_image_list)) teamid = UL
16  IF (any(mype == LL_image_list)) teamid = LL
17  IF (any(mype == UR_image_list)) teamid = UR
18  IF (any(mype == LR_image_list)) teamid = LR
19  FORM TEAM (teamid, t)
20
21  a = 3.14
22
23  CHANGE TEAM (t, b[2,*] => a)
24  ! Inside change team, image pattern for B is a 2 x 2 grid
25  b(5,5) = b(1,1)[2,1]
26
27  ! Outside the team addressing:
28
29  newpe = THIS_IMAGE()
30  SELECT CASE (team_id())
31  CASE (UL)
32    IF (newpe == 3) THEN
33      b(:,10) = b(:,1)[1, 1, TEAM_ID=UR] ! Right column of UL gets
34                                          ! left column of UR
35    ELSE IF (newpe == 4) THEN
36      b(:,10) = b(:,1)[2, 1, TEAM_ID=UR]
37    END IF
38  CASE (LL)
39    ! Similar to complete column exchange across middle of the
40    ! original grid
41  END SELECT
42  END TEAM
43  END PROGRAM DEMO

```

44 A.1.3 Reducing the codimension of a coarray

45 This example illustrates how to use a subroutine to coordinate cross-image access to a coarray for row and column
46 processing.

```

47 PROGRAM row_column
48   USE, INTRINSIC :: iso_fortran_env, ONLY : team_type
49   IMPLICIT NONE
50
51   TYPE(team_type), target :: row_team, col_team
52   TYPE(team_type), pointer :: used_team

```

```

1     REAL, ALLOCATABLE :: a(:,:)[(:,:)]
2     INTEGER :: ip, na, p, me(2)
3
4     p = ... ; q = ... ! such that p*q == num_images()
5     na = ...           ! local problem size
6
7     ! allocate and initialize data
8     ALLOCATE(a(na,na)[p,*])
9     a = ...
10
11    me = this_image(a)
12
13    FORM TEAM(me(1), row_team, NEW_INDEX=me(2))
14    FORM TEAM(me(2), col_team, NEW_INDEX=me(1))
15
16    ! make a decision on whether to process by row or column
17    IF (...) THEN
18        used_team => row_team
19    ELSE
20        used_team => col_team
21    END IF
22
23    ... ! do local computations on a
24
25    CHANGE TEAM (used_team)
26
27    CALL further_processing(a, ...)
28
29    END TEAM
30    CONTAINS
31    SUBROUTINE further_processing(a, ...)
32        REAL :: a(:,:)[*]
33        INTEGER :: ip
34
35        ! update ip-th row or column submatrix
36        a(:,:)[ip] = ...
37
38        SYNC ALL
39        ... ! do further local computations on a
40
41    END SUBROUTINE
42    END PROGRAM row_column

```

43 A.2 Clause 6 notes

44 A.2.1 Example involving failed images

45 Parallel algorithms often use work sharing schemes based on a specific mapping between image indices and global
46 data addressing. To allow such programs to continue when one or more images fail, spare images can be used
47 to re-establish execution of the algorithm with the failed images replaced by spare images, while retaining the
48 image mapping.

49 The following example illustrates how this might be done. In this setup, failure cannot be tolerated for image 1
50 in the initial team.

```

1 PROGRAM possibly_recoverable_simulation
2   USE, INTRINSIC :: iso_fortran_env, ONLY: team_type, STAT_FAILED_IMAGE
3   IMPLICIT NONE
4   INTEGER, ALLOCATABLE :: failed_img(:)
5   INTEGER :: images_used, i, images_spare, status
6   INTEGER :: id[*], me[*]
7   TYPE(team_type) :: simulation_team
8   LOGICAL :: read_checkpoint, done[*]
9
10  images_used = ... ! A value slightly less num_images()
11  images_spare = num_images() - images_used
12  read_checkpoint = this_image() > images_used
13
14  setup : DO
15    me = this_image()
16    id = 1
17    IF (me > images_used) id = 2
18  !
19  ! Set up spare images as replacement for failed ones
20  IF (image_status(1) == STAT_FAILED_IMAGE) &
21    ERROR STOP "cannot recover"
22  IF (this_image() == 1) THEN
23    failed_img = failed_images()
24    k = images_used
25    DO i = 1, size(failed_img)
26      DO k = k+1, num_images()
27        IF (image_status(k) == 0) EXIT
28      END DO
29      IF (k > num_images()) ERROR STOP "cannot recover"
30      me[k] = failed_img(i)
31      id[k] = 1
32    END DO
33    images_used = k
34  END IF
35  !
36  ! Set up a simulation team of constant size.
37  ! id == 2 does not participate in team execution
38  FORM TEAM (id, simulation_team, NEW_INDEX=me, STAT=status)
39  simulation : CHANGE TEAM (simulation_team, STAT=status)
40  IF (status==STAT_FAILED_IMAGE) EXIT simulation
41  IF (TEAM_ID() == 1) THEN
42    iter : DO
43      CALL simulation_procedure(read_checkpoint, status, done)
44    ! simulation_procedure:
45    !   sets up required objects (maybe coarrays)
46    !   reads checkpoint if requested
47    !   returns status on its internal synchronizations
48    !   returns .TRUE. in done once complete
49    read_checkpoint = .FALSE.
50    IF (status == STAT_FAILED_IMAGE) THEN
51      read_checkpoint = .TRUE.
52    EXIT simulation
53    ELSE IF (done)
54      EXIT iter
55    END IF

```

```

1         END DO iter
2     END IF
3     END TEAM simulation (STAT=status)
4     SYNC ALL (STAT=status)
5     IF (this_image() > images_used) done = done[1]
6     IF (done) EXIT setup
7     END DO setup
8 END PROGRAM possibly_recoverable_simulation

```

9 Supporting fail-safe execution imposes obligations on library writers who use the parallel language facilities. Every
10 synchronization statement, allocation or deallocation of coarrays, or invocation of a collective procedure must
11 specify a synchronization status variable, and implicit deallocation of coarrays must be avoided. In particular,
12 coarray module variables that are allocated inside the team execution context are not persistent.

13 A.3 Clause 7 notes

14 A.3.1 EVENT_QUERY example

15 The following example illustrates the use of events via a program in which image 1 acts as master and distributes
16 work items to the other images. Only one work item at a time can be active on a worker image, and each deals
17 with the result (e.g. via I/O) without directly feeding data back to the master image.

18 Because the work items are not expected to be balanced, the master keeps cycling through all images to find one
19 that is waiting for work.

20 An event is posted by each worker to indicate that it has completed its work item. Since the corresponding
21 variables are needed only on the master, we place them in an allocatable array component of a coarray. An event
22 on each worker is needed for the master to post the fact that it has made a work item available for it.

```

23 PROGRAM work_share
24     USE, INTRINSIC :: iso_fortran_env, ONLY: event_type
25     USE :: mod_work, ONLY: & ! Module that creates work items
26         work, & ! Type for holding a work item
27         create_work_item, & ! Function that creates work item
28         process_item, & ! Function that processes an item
29         work_done ! Logical function that returns true
30                 ! if all work done
31
32     TYPE :: worker_type
33         TYPE(event_type), ALLOCATABLE :: free(:)
34     END TYPE
35     TYPE(event_type) :: submit[*] ! Post when work ready for a worker
36     TYPE(worker_type) :: worker[*] ! Post when worker is free
37     TYPE(work) :: work_item[*] ! Holds the data for a work item
38     INTEGER :: count, i, nbusy[*]
39
40     IF (this_image() == 1) THEN
41         ! Get started
42         ALLOCATE(worker%free(2:num_images()))
43         nbusy = 0 ! This holds the number of workers working
44         DO i = 2, num_images() ! Start the workers working
45             IF (work_done()) EXIT
46             nbusy = nbusy + 1
47             work_item[i] = create_work_item()
48             EVENT POST (submit[i])

```

```

1      END DO
2      ! Main work distribution loop
3      master : DO
4          image : DO i = 2, num_images()
5              CALL EVENT_QUERY(worker%free(i), count)
6              IF (count == 0) CYCLE image! Worker is not free
7              EVENT WAIT (worker%free(i))
8              nbusy = nbusy - 1
9              IF (work_done()) CYCLE
10             nbusy = nbusy + 1
11             work_item[i] = create_work_item()
12             EVENT POST (submit[i])
13         END DO image
14         IF ( nbusy==0 ) THEN ! All done. Exit on all images.
15             DO i = 2, num_images()
16                 EVENT POST (submit[i])
17             END DO
18             EXIT master
19         END IF
20     END DO master
21 ELSE
22     ! Work processing loop
23     worker : DO
24         EVENT WAIT (submit)
25         IF (nbusy[1] == 0) EXIT
26         CALL process_item(work_item)
27         EVENT POST (worker[1]%free(this_image()))
28     END DO worker
29 END IF
30 END PROGRAM work_share

```

31 A.3.2 EVENT_QUERY example that tolerates image failure

32 This example is an adaptation of the example of A.2.1 to make it able to execute in the presence of the failure of
33 one or more of the worker images. The function create_work_item now accepts an integer argument to indicate
34 which work item is required. It is assumed that the work items are indexed 1, 2, It is also assumed that if
35 an image fails while processing a work item, that work item can subsequently be processed by another image.

```

36 PROGRAM work_share
37     USE, INTRINSIC :: iso_fortran_env, ONLY: event_type
38     USE :: mod_work, ONLY:  & ! Module that creates work items
39         work,                & ! Type for holding a work item
40         create_work_item, & ! Function that creates work item
41         process_item,      & ! Function that processes an item
42         work_done          ! Logical function that returns true
43                             ! if all work done
44
45     TYPE :: worker_type
46         TYPE(event_type), ALLOCATABLE :: free(:)
47     END TYPE
48     TYPE(event_type) :: submit[*] ! Whether work ready for a worker
49     TYPE(worker_type) :: worker[*] ! Whether worker is free
50     TYPE(work) :: work_item[*] ! Holds the data for a work item
51     INTEGER :: count, i, k, kk, nbusy[*], np, status
52     INTEGER, ALLOCATABLE :: working(:) ! Items being worked on

```



```

1  INTEGER, ALLOCATABLE :: pending(:) ! Items pending after image failure
2
3  IF (this_image() == 1) THEN
4      ! Get started
5      ALLOCATE(worker%free(2:num_images()))
6      ALLOCATE(working(2:num_images()), pending(num_images()-1))
7      nbusy = 0           ! This holds the number of workers working
8      k = 1              ! Index of next work item
9      np = 0            ! Number of work items in array pending
10     DO i = 2, num_images() ! Start the workers working
11         IF (work_done()) EXIT
12         working(i) = 0
13         CALL EVENT_QUERY(submit[i],count,STAT=status) ! Test image i
14         IF (status==STAT_FAILED_IMAGE) CYCLE
15         work_item[i] = create_work_item(k)
16         working(i) = k
17         k = k + 1
18         nbusy = nbusy + 1
19         EVENT POST (submit[i], STAT=status)
20     END DO
21     ! Main work distribution loop
22     master : DO
23         image : DO i = 2, num_images()
24             CALL EVENT_QUERY(submit[i],count,STAT=status) ! Test image i
25             IF (status==STAT_FAILED_IMAGE) THEN          ! Image i has failed
26                 IF (working(i)>0) THEN                  ! It failed while working
27                     np = np + 1
28                     pending(np) = working(i)
29                     working(i) = 0
30                 END IF
31                 CYCLE image
32             END IF
33             CALL EVENT_QUERY(worker%free(i), count)
34             IF (count == 0) CYCLE image                  ! Worker is not free
35             EVENT WAIT (worker%free(i))
36             nbusy = nbusy - 1
37             IF (np>0) THEN
38                 kk = pending(np)
39                 np = np - 1
40             ELSE
41                 IF (work_done()) CYCLE image
42                 kk = k
43                 k = k + 1
44             END IF
45             nbusy = nbusy + 1
46             working(i) = kk
47             CALL EVENT_QUERY(submit[i],count,STAT=status) ! Test image i
48             IF (status/=STAT_FAILED_IMAGE) &
49                 work_item[i] = create_work_item(kk)
50             EVENT POST (submit[i],STAT=status)
51             ! If image i has failed, this will not hang and the failure
52             ! will be handled on the next iteration of the loop
53         END DO image
54         IF ( nbusy==0 ) THEN ! All done. Exit on all images.
55             DO i = 2, num_images()

```

```

1         EVENT POST (submit[i],STAT=status)
2         IF (status==STAT_FAILED_IMAGE) CYCLE
3     END DO
4     EXIT master
5     END IF
6 END DO master
7 ELSE
8     ! Work processing loop
9     worker : DO
10        EVENT WAIT (submit)
11        IF (nbusy[1] == 0) EXIT worker
12        CALL process_item(work_item)
13        EVENT POST (worker[1]%free(this_image()))
14    END DO worker
15 END IF
16 END PROGRAM work_share

```

17 A.3.3 EVENTS example

18 A tree is a graph in which every node except one has a single “parent” node to which it is connected by an edge.
19 The node without a parent is the “root”. The nodes that have a given node as parent are the “children” of that
20 node. The root is at level 1, its children are at level 2, etc.

21 A multifrontal code to solve a sparse set of linear equations involves a tree. Work at a node starts after work at
22 all its children is complete and their data has been passed to it.

23 Here we assume that all nodes have been assigned to images. Each image has a list of its nodes and these are
24 ordered in decreasing tree level (all those at level L preceding those at level $L - 1$). For each node, array elements
25 hold the number of children, details about the parent and an event variable. This allows the processing to proceed
26 asynchronously subject to the rule that a parent must wait for all its children as follows:

```

27 PROGRAM TREE
28     USE, INTRINSIC :: ISO_FORTRAN_ENV
29     INTEGER,ALLOCATABLE :: NODE(:) ! Tree nodes that this image handles
30     INTEGER,ALLOCATABLE :: NC(:)   ! NODE(I) has NC(I) children
31     INTEGER,ALLOCATABLE :: PARENT(:), SUB(:)
32         ! The parent of NODE(I) is NODE(SUB(I))[PARENT(I)]
33     TYPE(EVENT_TYPE),ALLOCATABLE :: DONE(:)[*]
34     INTEGER :: I, J, STATUS
35 ! Set up the tree, including allocation of all arrays.
36 DO I = 1, SIZE(NODE)
37     ! Wait for children to complete
38     EVENT WAIT(DONE(I),UNTIL_COUNT=NC(I),STAT=STATUS)
39     IF (STATUS/=0) EXIT
40
41     ! Process node, using data from children
42     IF (PARENT(I)>0) THEN
43         ! Node is not the root.
44         ! Place result on image PARENT(I) for node NODE(SUB)[PARENT(I)]
45         ! Tell PARENT(I) that this has been done.
46         EVENT POST(DONE(SUB(I))[PARENT(I)],STAT=STATUS)
47         IF (STATUS/=0) EXIT
48     END IF
49 END DO
50 END PROGRAM TREE

```

1 A.4 Clause 8 notes

2 A.4.1 Collective subroutine examples

3 The following example computes a dot product of two scalar coarrays using the `co_sum` intrinsic to store the
4 result in a noncoarray scalar variable:

```
5  subroutine codot(x,y,x_dot_y)
6      real :: x[*],y[*],x_dot_y
7      x_dot_y = x*y
8      call co_sum(x_dot_y)
9  end subroutine codot
```

10 The function below demonstrates passing a noncoarray dummy argument to the `co_max` intrinsic. The function
11 uses `co_max` to find the maximum value of the dummy argument across all images. Then the function flags all
12 images that hold values matching the maximum. The function then returns the maximum image index for an
13 image that holds the maximum value:

```
14  function find_max(j) result(j_max_location)
15      integer, intent(in) :: j
16      integer j_max,j_max_location
17      j_max = j
18      call co_max(j_max)
19  ! Flag images that hold the maximum j
20      if (j==j_max) then
21          j_max_location = this_image()
22      else
23          j_max_location = 0
24      end if
25  ! Return highest image index associated with a maximal j
26      call co_max(j_max_location)
27  end function find_max
```

28 A.4.2 Atomic memory consistency

29 A.4.2.1 Relaxed memory model

30 Parallel programs sometimes have apparently impossible behavior because data transfers and other messages can
31 be delayed, reordered and even repeated, by hardware, communication software, and caching and other forms of
32 optimization. Requiring processors to deliver globally consistent behavior is incompatible with performance on
33 many systems. Fortran specifies that all ordered actions will be consistent (2.3.5 and 8.5 in ISO/IEC 1539-1:2010),
34 but all consistency between unordered segments is deliberately left processor dependent or undefined. Depending
35 on the hardware, this can be observed even when only two images and one mechanism are involved.

36 A.4.2.2 Examples with atomic operations

37 When variables are being referenced (atomically) from segments that are unordered with respect to the segment
38 that is atomically defining or redefining the variables, the results are processor dependent. This supports use
39 of so-called “relaxed memory model” architectures, which can enable more efficient execution on some hardware
40 implementations.

41 The following examples assume the following declarations:

```
42  MODULE example
43      USE, INTRINSIC :: ISO_FORTRAN_ENV
44      INTEGER(ATOMIC_INT_KIND) :: x[*] = 0, y[*] = 0
```

1 Example 1:

2 With `x[j]` and `y[j]` still in their initial state (both zero), image `j` executes the following sequence of statements:

```
3 CALL ATOMIC_DEFINE(x,1)
4 CALL ATOMIC_DEFINE(y,1)
```

5 and image `k` executes the following sequence of statements:

```
6 DO
7   CALL ATOMIC_REF(tmp,y[j])
8   IF (tmp==1) EXIT
9 END DO
10 CALL ATOMIC_REF(tmp,x[j])
11 PRINT *,tmp
```

12 The final value of `tmp` on image `k` can be either 0 or 1. That is, even though image `j` thinks it wrote `x[j]` before
13 writing `y[j]`, this ordering is not guaranteed on image `k`.

14 There are many aspects of hardware and software implementation that can cause this effect, but conceptually this
15 example can be thought of as the change in the value of `y` propagating faster across the inter-image connections
16 than the change in the value of `x`.

17 Changing the execution on image `j` by inserting

```
18 SYNC MEMORY
```

19 in between the definitions of `x` and `y` is not sufficient to prevent unexpected results; even though `x` and `y` are
20 being updated in ordered segments, the references from image `k` are both from a segment that is unordered with
21 respect to image `j`.

22 To guarantee the expected value for `tmp` of 1 at the end of the code sequence on image `k`, it is necessary to ensure
23 that the atomic reference on image `k` is in a segment that is ordered relative to the segment on image `j` that
24 defined `x[j]`; `SYNC MEMORY` is certainly necessary, but not sufficient unless it is somehow synchronized.

25 Example 2:

26 With the initial state of `x` and `y` on image `j` (i.e. `x[j]` and `y[j]`) still being zero, execution of

```
27 CALL ATOMIC_REF(tmp,x[j])
28 CALL ATOMIC_DEFINE(y[j],1)
29 PRINT *,tmp
```

30 on image `k1`, and execution of

```
31 CALL ATOMIC_REF(tmp,y[j])
32 CALL ATOMIC_DEFINE(x[j],1)
33 PRINT *,tmp
```

34 on image `k2`, in unordered segments, might print the value 1 both times.

35 This can happen by such mechanisms as “load buffering”; one might imagine that what is happening is that the
36 writes (`ATOMIC_DEFINE`) are overtaking the reads (`ATOMIC_REF`).

37 It is likely that insertion of `SYNC MEMORY` between the calls to `ATOMIC_REF` and `ATOMIC_DEFINE` will be sufficient to
38 prevent this anomalous behavior, but that is only guaranteed by the standard if the `SYNC MEMORY` executions
39 cause an ordering between the relevant segments on images `k1` and `k2`.

1 Example 3:

2 Because there are no segment boundaries implied by collective subroutines, with the initial state as before,
3 execution of

```

4     IF (THIS_IMAGE()==1) THEN
5         CALL ATOMIC_DEFINE(x[3],23)
6         y = 42
7     ENDIF
8     CALL CO_BROADCAST(y,1)
9     IF (THIS_IMAGE()==2) THEN
10        CALL ATOMIC_REF(tmp,x[3])
11        PRINT *,y,tmp
12    END IF

```

13 could print the values 42 and 0.

14 Example 4:

15 Assuming the declarations

```

16 INTEGER(ATOMIC_INT_KIND) :: x[*]= 0, z = 0

```

17 the statements

```

18 CALL ATOMIC_ADD(x[1], 1)           ! (A)
19 IF (THIS_IMAGE() == 2) THEN
20     wait : DO
21         CALL ATOMIC_REF(z, x[1])   ! (B)
22         IF (z == NUM_IMAGES()) EXIT wait
23     END DO wait                    ! (C)
24 END IF

```

25 will execute the “wait” loop on image 2 until all images have completed statement (A). The updates of x[1] are
26 performed by each image in the same manner, but arbitrary order. Because the result from the complete set
27 of updates will eventually become visible by execution of statement (B) for some loop iteration on image 2, the
28 termination condition is guaranteed to be eventually fulfilled, provided that no image failure occurs, every image
29 executes the above code, and no other code is executed in an unordered segment that performs updates to x[1].
30 Furthermore, if two SYNC MEMORY statements are inserted in the above code before statement (A) and after
31 statement (C), respectively, the segment started by the second SYNC MEMORY on image 2 is ordered after the
32 segments on all images that end with the first SYNC MEMORY.